

SIPROTEC 4 7SD52/53

Multi-End Differential and Distance Protection in One Relay



Fig. 7/42
SIPROTEC 4
7SD52/53 differential protection relay

Description

The 7SD52/53 relay provides full scheme differential protection and incorporates all functions usually required for the protection of power lines. It is designed for all power and distribution levels and protects lines with two up to six line ends. The relay is designed to provide high-speed and phase-selective fault clearance. The relay uses fiber-optic cables or digital communication networks to exchange telegrams and includes special features for the use in multiplexed communication networks. Also pilot wires connections can be used with an external converter. This contributes toward improved reliability and availability of the electrical power system.

The relay is suitable for single and three-phase tripping applications for two up to six line ends. Also, transformers and compensation coils within the differential protection zone are protected as are serial and parallel-compensated lines and cables. The relays may be employed with any type of system earthing.

The relay also provides a full-scheme and non-switched distance protection as an optional main 2 protection. Several teleprotection schemes ensure maximum selectivity and high-speed tripping time.

The units measure the delay time in the communication networks and adaptively match their measurements accordingly.

A special GPS-option allows the use of the relays in communication networks, where the delay time in the transmit and receive path may be quite different.

The 7SD52/53 has the following features:

- 2 full-scheme main protections in one unit (differential and distance protection)
- High-speed tripping 10 - 15 ms
- The serial protection data interfaces (R2R interfaces) of the relays can flexibly be adapted to the requirements of all communication media available.
- If the communication method is changed, flexible retrofitting of communication modules to the existing configuration is possible.
- Tolerates loss of one data connection in a ring topology (routing in 120 ms). The differential protection scheme is fully available in a chain topology.
- Browser-based commissioning tool.
- Fault locator for one and two terminal measurement for high accuracy on long lines with high load and high fault resistance.
- Capacitive charge current compensation increases the sensitivity of the differential protection on cables and long lines.

Function overview

Protection functions

- Differential protection with phase-segregated measurement (87L, 87T)
- Restricted earth-fault protection (87N) if a transformer is within the protection zone
- Sensitive meas. stage f. high-resist. faults
- Non-switched distance protection with 7 measuring systems (21/21N)
- High resistance ground (earth)-fault protection for single and three-pole tripping (50N/51N/67N)
- Phase-selective intertripping (85)
- Earth-fault detection in isolated and resonant-earthed networks
- Tele (pilot) protection (85/21, 85/67N)
- Weak-infeed protection (27WI)
- Fault locator (FL)
- Power swing detection/tripping (68/68T)
- 3-stage overcurrent protection (50, 50N, 51, 51N)
- STUB bus protection (50 STUB)
- Switch-onto-fault protection (50HS)
- Over/undervoltage protection (59/27)
- Over/underfrequency protection (81O/U)
- Auto-reclosure (79), Synchro-check (25)
- Breaker failure protection (50BF)
- Overload protection (49)
- Lockout function (86)

Control functions

- Commands f. ctrl of CB and isolators

Monitoring functions

- Self-supervision of relay and protection data (R2R) communication
- Trip circuit supervision (74TC)
- Measured-value supervision
- Oscillographic fault recording
- Event logging/fault logging
- Switching statistics

Front design

- User-friendly local operation
- PC front port for relay setting
- Function keys and 14 LEDs f. local alarm

Communication interfaces

- 2 serial protection data (R2R) interfaces for ring and chain topology
- Front interface for connecting a PC
- System interface for connection to a control system via various protocols
 - IEC 61850 Ethernet
 - IEC 60870-5-103
 - PROFIBUS-FMS/-DP and DNP 3.0
- Rear-side service/modem interface
- Time synchronization via IRIG-B or DCF77 or system interface

Application

ANSI		ANSI	
(87L)	ΔI for lines / cables	(50HS)	Instantaneous high-current tripping (switch-onto-fault)
(87T)	ΔI for lines / cables with transformers	(59)(27)	Overvoltage/undervoltage protection
(87N)	Low impedance restricted earth-fault protection for transformers	(81O/U)	Over/underfrequency protection
(85)	Phase-selective intertrip, remote trip	(25)	Synchro-check
(86)	Lockout function	(79)	Single or three-pole auto-reclosure with new adaptive technology
(21)(21N)	Distance protection	(49)	Overload protection
(FL)	Fault locator	(50BF)	Breaker failure protection
(68)(68T)	Power swing detection/tripping	(74TC)	Trip circuit supervision
(85/21)	Teleprotection for distance protection	(50-STUB)	STUB bus protection
(27WI)	Weak-infeed protection		
(50N)(51N)(67N)	Directional earth(ground)-fault protection		
(85/67N)	Teleprotection for earth (ground)-fault protection		
(50)(50N)(51)(51N)	Three-stage overcurrent protection		

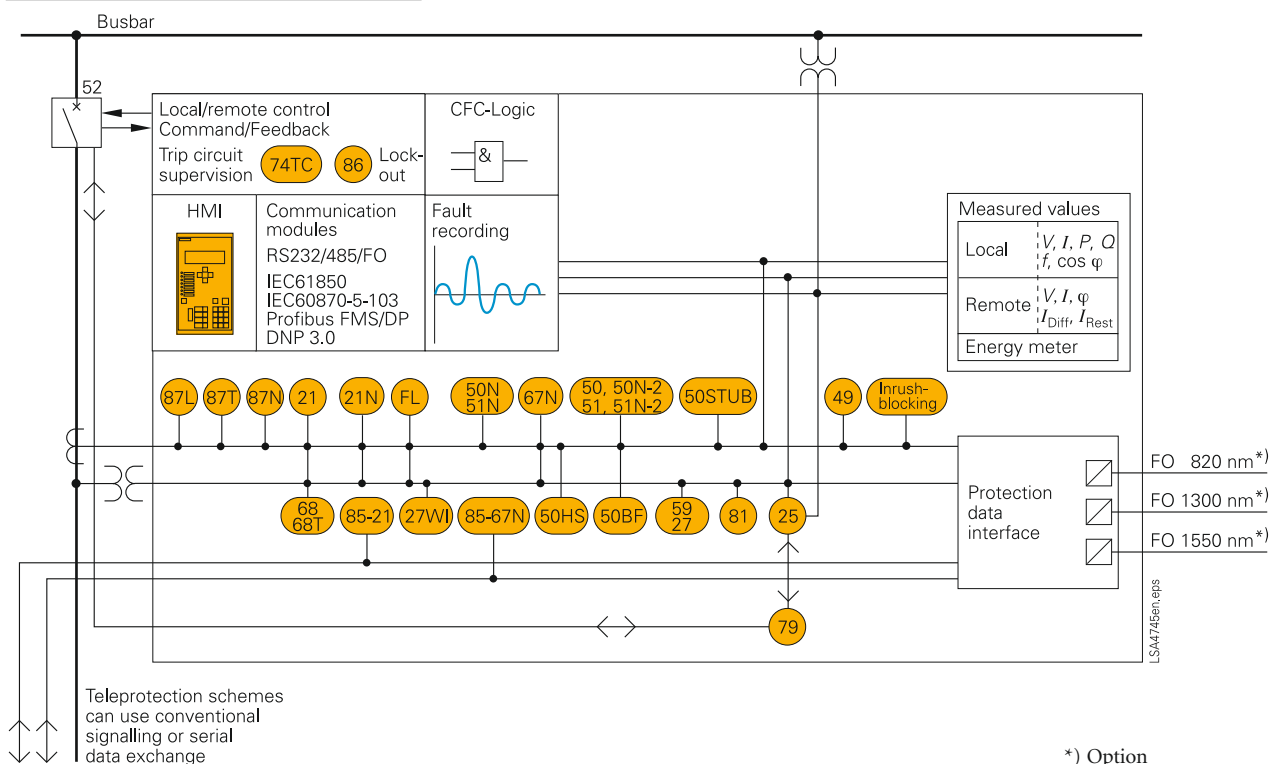


Fig. 7/43

Application

Typical applications

SIPROTEC 7SD52/53 is a full-scheme differential protection relay for two up to six line ends, incorporating all the additional functions for protection of overhead lines and cables at all voltage levels. Also transformers and compensation coils within the protection zone are protected. The 7SD52/53 is suitable for single-pole and three-pole tripping. The power system star point can be solid or impedance-grounded (earthed), resonant-earthed via Peterson coil or isolated. On the TAP-line, the 7SD52/53 differential relay is connected to current (CT) and optionally voltage (VT) transformers. For the differential functions, only CTs are necessary. By connecting the relay to VTs, the integrated "main 2" distance protection can be applied (full-scheme, nonswitched). Therefore, no separate distance protection relay is required.

The link to the other relays is made by multi-mode or mono-mode FO cables. There are 5 options available, which correspondingly cover:

- 820 nm, up to 1.5 km, multi-mode
- 820 nm, up to 3.5 km, multi-mode
- 1300 nm, up to 24 km, mono-mode
- 820 nm support of the IEEE C37.94 interface
- 1300 nm, up to 60 km, mono-mode
- 1550 nm, up to 100 km, mono-mode

Direct fiber-optic connection offers high-speed data exchange with 512 kbit/s and improves the speed for remote signaling.

At the main line two differential relays are connected to CTs. The communication is made via a multiplexed communication network.

The 7SD52/53 offers many features to reliably and safely handle data exchange via communication networks.

Depending on the bandwidth available in the communication system, 64, 128 or 512 kbits/s can be selected for the X21 (RS422) interface; the G703 interface with 64 kbit/s, and G703-E1 (2,048 kbit/s) or G703-T1 (1,554 kbit/s). Furthermore the 7SD610 supports the IEEE C37.94 interface with 1/2/4 and 8 timeslots.

The connection to the communication device is effected via cost-effective 820 nm interface with multi-mode FO cables.

A communication converter converts the optical to electrical signals. This offers an interference-free and isolated connection between the relay and the communication device.

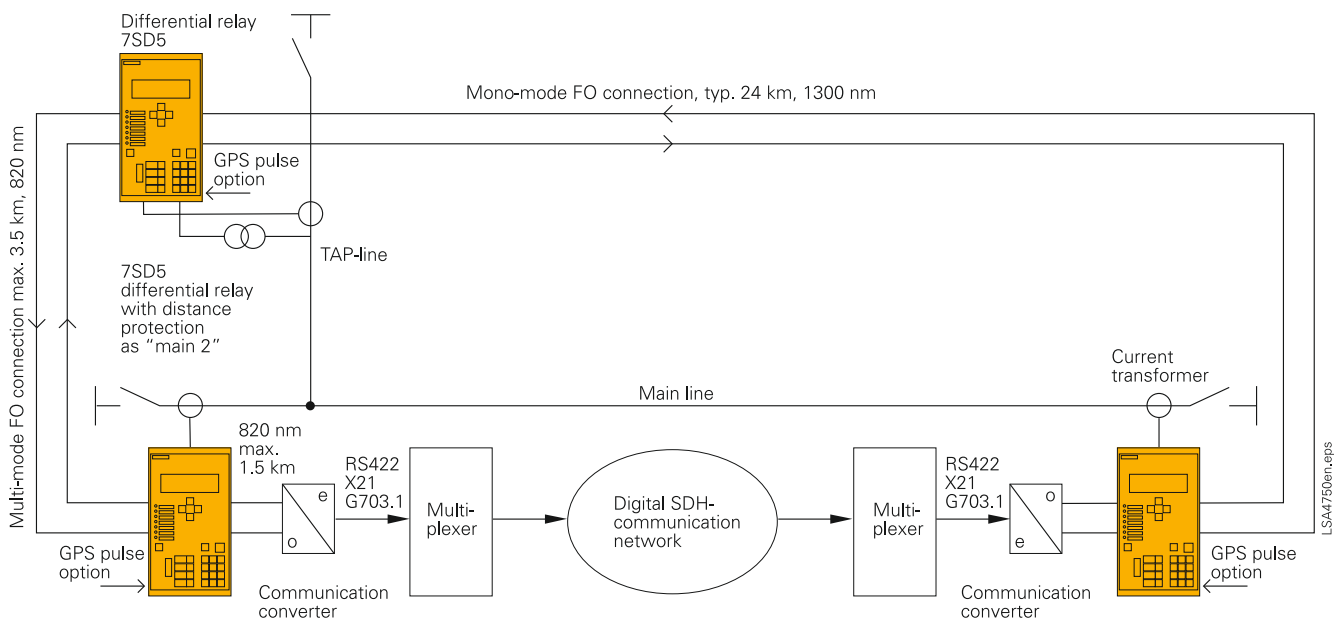


Fig. 7/44 Application for three line ends (Ring topology)

Cost-effective power system management

The SIPROTEC 4 units are numerical relays which also provide control and monitoring functions and therefore support the user in view of a cost-effective power system management. The security and reliability of power supply is increased as a result of minimizing the use of hardware.

The local operation has been designed according to ergonomic criteria. Large, easy-to-read backlit displays are provided.

The SIPROTEC 4 units have a uniform design and a degree of functionality which represents a benchmark-level of performance in protection and control. If the requirements for protection, control or interlocking change, it is possible in the majority of cases to implement such changes by means of parameterization using DIGSI 4 without having to change the hardware.

The use of powerful microcontrollers and the application of digital measured-value conditioning and processing largely suppresses the influence of higher-frequency transients, harmonics and DC components.

Construction

Connection techniques and housing with many advantages

1/3, 1/2, 2/3, and 1/1-rack sizes:

These are the available housing widths of the 7SD52/53 relays, referred to a 19" module frame system. This means that previous models can always be replaced. The height is a uniform 245 mm for flush-mounting housings and 266 mm for surface-mounting housings for all housing widths. All cables can be connected with or without ring lugs. Plug-in terminals are available as an option. It is thus possible to employ pre-fabricated cable harnesses. In the case of surface mounting on a panel, the connection terminals are located above and below in the form of screw-type terminals. The communication interfaces are located in a sloped case at the top and bottom of the housing.



Fig. 7/45
Flush-mounting housing
with screw-type terminals

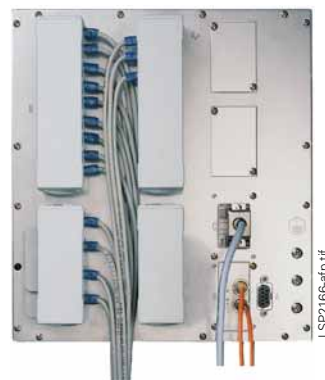


Fig. 7/46
Rear view of flush-mounting housing
with covered connection terminals and wirings



Fig. 7/47
Surface-mounting housing with screw-type
terminals



Fig. 7/48
Communication interfaces
in a sloped case in a surface-
mounting housing

Protection functions

Differential protection (ANSI 87L, 87T, 87N)

The differential protection function has the following features:

- It is possible to select the operating mode as "main" or as "main 1", if the back-up distance protection is activated as "main 2".
- Measurements are performed separately for each phase; thus the trip sensitivity is independent of the fault type.
- An adaptive, sensitive measurement method with high sensitivity for differential fault currents below the rated current offers the detection of highly resistive faults. This trip element uses special filters, which offers high security even with high level DC-components in the short-circuit current. The trip time of this stage is about 30 ms.
- A high-set differential trip stage which clears differential fault currents higher than the rated current within 10 – 15 ms offers fast tripping time and high-speed fault clearance time.
- When a long line or cable is switched on, transient charge currents load the line. To avoid a higher setting of the sensitive differential trip stage, this setpoint may be increased for a settable time. This offers greater sensitivity under normal load conditions.
- With the setting of the CT-errors the relay automatically calculates the restraint/stabilization current and adapts its permissible sensitivity according to the CT's data in the differential configuration, optimizing sensitivity.
- Different CT ratios at the line ends are handled inside the relay. The mismatch of 1 to 6 is allowed.
- The differential protection trip can be guarded with an overcurrent pickup. Thus differential current and overcurrent lead to a final trip decision.
- Easy to set tripping characteristic. Because the relay works adaptively, only the setpoint $I_{Diff} >$ (sensitive stage) and $I_{Diff} >>$ (high-set current differential stage) must be set according to the charge current of the line/cable.
- With an optional capacitive charge current compensation, the sensitivity can be increased to 40 % of the normal setting of $I_{DIFF} >$. This function is recommended for long cables and long lines.

- Differential and restraint currents are monitored continuously during normal operation and are displayed as operational measurements.
- High stability during external faults even with different current transformers saturation level. For an external fault, only 5 ms saturation-free time are necessary to guarantee the stability of the differential configuration.
- With transformers or compensation coils in the protection zone, the sensitive trip stage can be blocked by an inrush detection function. It works with the second harmonic of the measured current which is compared with the fundamental component.
- With transformers in the protection zone, vector group adaptation and matching of different CT ratios are carried out in the relay. Additionally, the zero-sequence current flowing through an earthed neutral is eliminated from the differential measurement. The 7SD52/53 therefore works like a transformer differential relay, whereas the line ends may be far away.
- A more sensitive protection for transformers within the protection zone is given by measurement of the star-point current on an earthed winding. Therefore the I_E current measuring input has to be used.
If the sum of the phase currents of winding is compared with the measured star-point current, a sensitive earth-current differential protection (REF) can be implemented.
This function is substantially more sensitive than the differential protection during faults to earth in a winding, detecting fault currents as small as 10 % of the transformer rated current.

Enhanced communication features for communication networks

The data required for the differential calculations are cyclically exchanged in full-duplex mode in form of synchronous, serial telegrams between the protection units. The telegrams are secured with CRC check sums, so that transmission errors in a communication network are immediately detected.

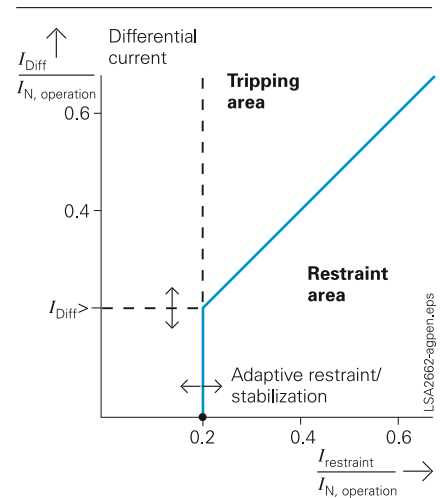


Fig. 7/49 Tripping characteristic

- Data communication is immune to electromagnetic interference because fiber-optic cables are employed in the critical region
- Supervision of each individual incoming telegram and of the entire communication path between the units without additional equipment.
- Unambiguous identification of each unit is ensured by assignment of a settable communication address within a differential protection topology. Only those units mutually known to each other can cooperate. Incorrect interconnection of the communication links results in blocking of the protection system.
- Detection of reflected telegrams in the communication system.
- Detection of delay time changes in communication networks.
- Measurement of the delay time to the remote line ends with dynamic compensation of the delay in the differential measurement. Supervision of the maximum permissible delay time is included.
- Generation of alarms on heavily disturbed communication links. Faulty telegram counters are available as operational measurement.
- With a GPS high-precision 1-s pulse from a GPS receiver the relays can be synchronized with an absolute, exact time at each line end. In this way, the delay in the receive and transmit path can be measured exactly. With this optional feature the relay can be used in communication networks where this delay times are quite different.

Protection functions

Phase-selective intertrip and remote trip/indications

Normally the differential fault current is calculated for each line end nearly at the same time. This leads to fast and uniform tripping times. Under weak infeed conditions, especially when the differential function is combined with an overcurrent pickup a phase-selective intertrip offers a tripping of all line ends.

- 7SD52/53 has 4 intertrip signals which are transmitted in high-speed (< 20 ms) to the other line ends. These intertrip signals can also be initiated by an external relay via binary inputs and therefore be used to indicate, for example, a directional decision of the backup distance relay.
- In addition, 4 high-speed remote trip signals are available, which may be initiated by an external or internal event.
- 24 remote signals can be freely assigned to inputs and outputs at each line end and are circulating between the different devices.

Communication topologies / modes of operation

The differential relays may work in a ring or daisy chain line topology. Use of a test mode offer advantages under commissioning and service conditions.

- The system tolerates the loss of one data connection in a ring topology. The ring topology is rerouted within 20 ms forming then a chain topology, while the differential protection function is immediately reactivated.
- When the communication connections need to be reduced or when these are not available, the whole system is able to function without interruption as chain topology. At the line ends, only cost-effective 7SD52/53 relays with one protection data interface are necessary for this application.
- The two-end line is a special case, because when the main connection is interrupted, the communication switches over from a main path to a secondary path. This hot standby transmission function ensures a high availability of the system and protects differential protection against communication route failure on important lines.

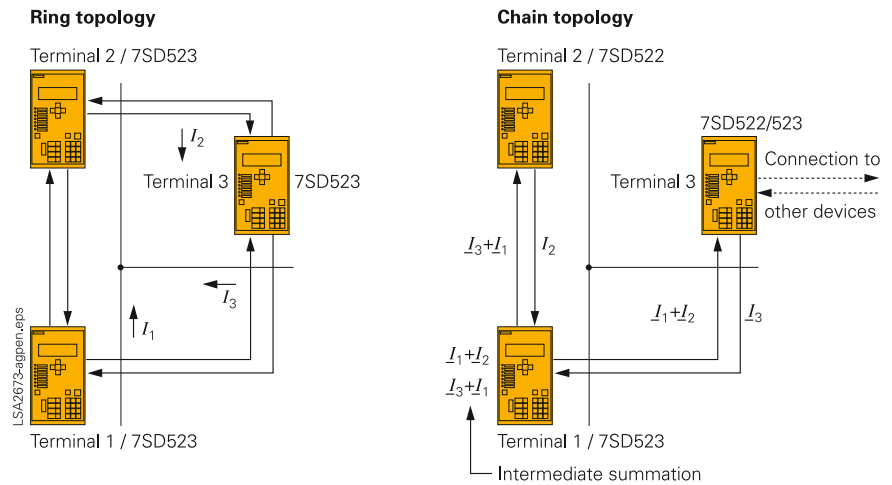


Fig. 7/50 Differential protection in ring or chain topology

- In a ring topology, one line end can be logged out from the differential protection topology for service or maintenance reasons by a signal via binary input. Checks for the breaker position and load current are made before this logout is initiated. In a chain topology, the relays at the end of the line can be logged out from the differential protection topology.
- The whole configuration can be set up into a test mode. All functions and indications are available except the breakers are not tripped. The local relay can be tested and no trip or intertrip reaction is effected by the other relays.

Protection functions

Distance protection (ANSI 21, 21N)

7SD52/53 provides a non-switched distance protection featuring all well-proven algorithms of 7SA522 and 7SA6. It is possible to select the operating mode "main" or "main 2", if the back-up differential is activated as "main 1". By parallel calculation and monitoring of all six impedance loops, a high degree of sensitivity and selectivity is achieved for all types of faults. The shortest tripping time is less than one cycle. All methods of neutral-point connection (resonant earthing, isolated, solid or low-resistance earthing) are reliably dealt with. Single and three-pole tripping is possible. Overhead lines can be equipped with or without series capacitor compensation.

Quadrilateral and mho characteristics

The 7SD52/53 relay provides quadrilateral as well as mho zone characteristics. Both characteristics can be used separately for phase and ground (earth) faults. Resistance ground (earth) faults can, for instance, be covered with the quadrilateral characteristic and phase faults with the mho characteristic.

Alternatively, the quadrilateral characteristic is available with 4 different pickup methods:

- Overcurrent pickup $I >>$
- Voltage-dependent overcurrent pickup V/I
- Voltage-dependent and phase angle-dependent overcurrent pickup $V/I/\varphi$
- Impedance pickup $Z <$

Load zone

In order to guarantee a reliable discrimination between load operation and short-circuit – especially on long high loaded lines – the relay is equipped with a selectable load encroachment characteristic. Impedances within this load encroachment characteristic prevent the distance zones from unwanted tripping.

Absolute phase-selectivity

The distance protection incorporates a well-proven highly sophisticated phase selection algorithm. The pickup of unfaulted loops is reliably eliminated to prevent the adverse influence of currents and voltages in the fault-free loops. This phase selection algorithm achieves single-pole tripping and correct distance measurement in a wide application range.

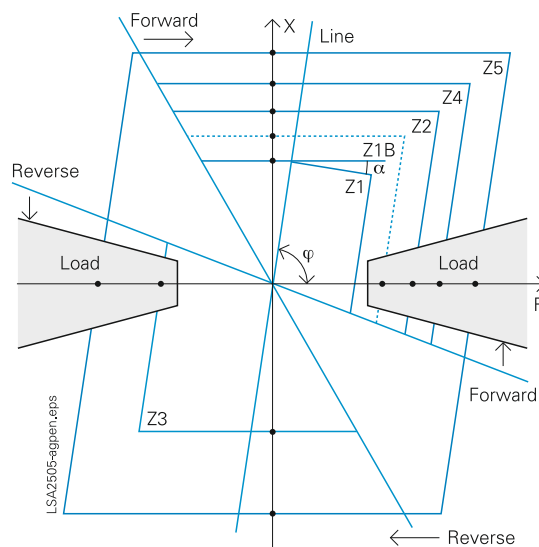


Fig. 7/51
Distance protection:
quadrilateral characteristic

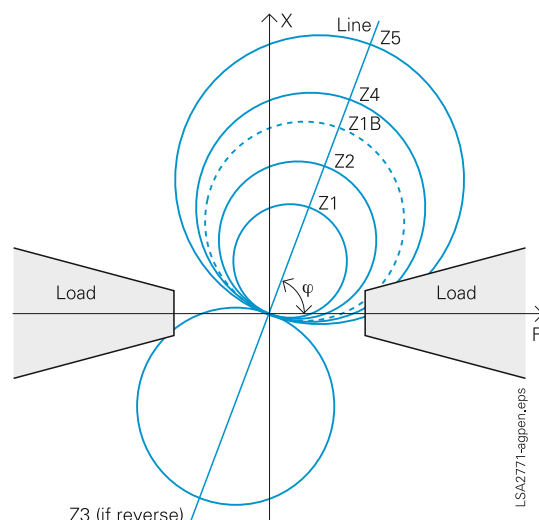


Fig. 7/52
Distance protection:
mho characteristic

Parallel line compensation

The influence of wrong distance measurement due to parallel lines can be compensated by feeding the neutral current of the parallel line to the relay. Parallel line compensation can be used for distance protection as well as for fault locating.

7 distance zones

6 independent distance zones and one separate overreach zone are available. Each distance zone has dedicated time stages, partly separate for single-phase or multi-phase faults. Ground (earth) faults are detected by monitoring the neutral current $3I_0$ and the zero-sequence voltage $3V_0$.

The quadrilateral tripping characteristic permits separate setting of the reactance X and the resistance R . The resistance section R can

be set separately for faults with and without earth involvement. This characteristic has therefore an optimal performance in case of faults with fault resistance. The distance zones can be set forward, reverse or non-directional. Sound phase polarization and voltage memory provides a dynamically unlimited directional sensitivity.

Mho

The mho tripping characteristic provides sound phase respectively memory polarization for all distance zones. The diagram shows characteristic without the expansion due to polarizing. During a forward fault the polarizing expands the mho circle towards the source so that the origin is included. This mho circle expansion guarantees safe and selective operation for all types of faults, even for close-in faults.

Protection functions

Elimination of interference signals

Digital filters render the unit immune to interference signals contained in the measured values. In particular, the influence of DC components, capacitive voltage transformers and frequency changes is considerably reduced. A special measuring method is employed in order to assure protection selectivity during saturation of the current transformers.

Measuring voltage monitoring

Tripping of the distance protection is blocked automatically in the event of failure of the measuring voltage, thus preventing spurious tripping.

The measuring voltage is monitored by the integrated fuse failure monitor. Distance protection is blocked if either the fuse failure monitor or the auxiliary contact of the voltage transformer protection switch operates and, in this case, the EMERGENCY definite-time overcurrent protection can be activated.

Power swing detection (ANSI 68, 68T)

Dynamic transient reactions, for instance short-circuits, load fluctuations, auto-reclosures or switching operations can cause power swings in the transmission network. During power swings, large currents along with small voltages can cause unwanted tripping of distance protection relays. To avoid uncontrolled tripping of the distance protection and to achieve controlled tripping in the event of loss of synchronism, the 7SD52/53 relay is equipped with an efficient power swing detection function. Power swings can be detected under symmetrical load conditions as well as during single-pole auto-reclosures.

Tele (pilot) protection for distance protection (ANSI 85-21)

A teleprotection function is available for fast clearance of faults up to 100 % of the line length. The following operating modes may be selected:

- PUTT, permissive underreaching zone transfer trip
- POTT, permissive overreaching zone transfer trip
- UNBLOCKING
- BLOCKING
- Directional comparison pickup
- Pilot-wire comparison
- Reverse interlocking

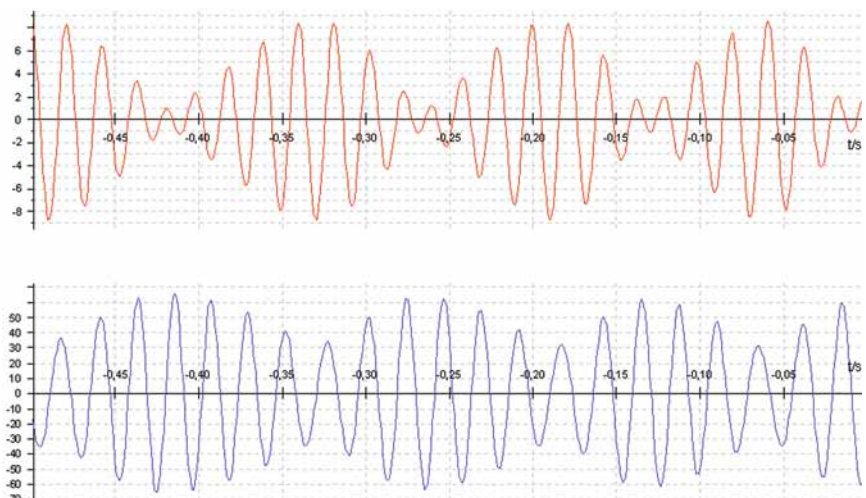


Fig. 7/53
Power swing current and voltage wave forms

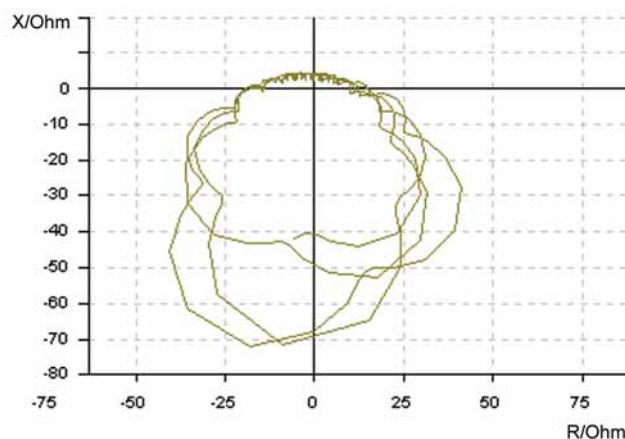


Fig. 7/54
Power swing
circle diagram

- DUTT, direct underreaching zone transfer trip (together with Direct Transfer Trip function)

The carrier send and receive signals are available as binary inputs and outputs and can be freely assigned to each physical relay input or output. At least one channel is required for each direction.

Common transmission channels are power-line carrier, microwave radio and fiber-optic links. The serial protection data interface can be used for direct connection to a digital communication network, fiber-optic or pilot-wire link as well.

7SD52/53 also permits the transfer of phase-selective signals. This feature is particularly advantageous as it ensures reliable single-pole tripping, if two single-pole faults occur on different lines. The transmission methods are suitable also for lines with three ends (three-terminal lines).

Phase-selective transmission is also possible with multi-end applications, if some user-specific linkages are implemented by way of the integrated CFC logic. During disturbances in the transmission receiver or on the transmission circuit, the teleprotection function can be blocked by a binary input signal without losing the zone selectivity. The control of the overreach zone Z1B (zone extension) can be switched over to the auto-reclosure function. A transient blocking function (Current reversal guard) is provided in order to suppress interference signals during tripping of parallel lines.

Protection functions

Direct transfer tripping

Under certain conditions on the power system it is necessary to execute remote tripping of the circuit-breaker. The 7SD52/53 relay is equipped with phase-selective “external trip inputs” that can be assigned to the received inter-trip signal for this purpose.

Weak-infeed protection: echo and/or trip (ANSI 27 W1)

To prevent delayed tripping of permissive schemes during weak or zero infeed situations, an echo function is provided. If no fault detector is picked up at the weak-infeed end of the line, the signal received here is returned as echo to allow accelerated tripping at the strong infeed end of the line. It is also possible to initiate tripping at the weak-infeed end. A phase-selective 1-pole or 3-pole trip is issued if a permissive trip signal (POTT or Unblock-ing) is received and if the phase-earth voltage drops correspondingly. As an option, the weak-infeed logic can be equipped according to a French specification.

Directional ground(earth)-fault protection for high-resistance faults (ANSI 50N, 51N, 67N)

In grounded (earthed) networks, it may happen that the distance protection sensitivity is not sufficient to detect high-resistance ground (earth) faults. The 7SD52/53 protection relay has therefore protection functions for faults of this nature.

The ground (earth)-fault overcurrent protection can be used with 3 definite-time stages and one inverse-time stage (IDMT). A 4th definite-time stage can be applied instead of the 1st inverse-time stage.

Inverse-time characteristics according to IEC 60255-3 and ANSI/IEEE are provided (see “Technical data”). An additional logarithmic inverse-time characteristic is also available.

The direction decision can be determined by the neutral current and the zero-sequence voltage or by the negative-sequence components V_2 and I_2 . In addition or as an alternative to the directional determination with zero-sequence voltage, the star-point current of a grounded (earthed) power transformer may also be used for polarization. Dual polarization applications can therefore be fulfilled. Alternatively, the direction can be determined by evaluation of zero-sequence

power. Each overcurrent stage can be set in forward or reverse direction or for both directions (non-directional). As an option the 7SD52/53 relay can be provided with a sensitive neutral (residual) current transformer. This feature provides a measuring range for the neutral (residual) current from 5 mA to 100 A with a nominal relay current of 1 A and from 5 mA to 500 A with a nominal relay current of 5 A. Thus the ground (earth)-fault overcurrent protection can be applied with extreme sensitivity.

The function is equipped with special digital filter algorithms, providing the elimination of higher harmonics. This feature is particularly important for low zero-sequence fault currents which usually have a high content of 3rd and 5th harmonics. Inrush stabilization and instantaneous switch-onto-fault trip can be activated separately for each stage as well.

Different operating modes can be selected. The ground(earth)-fault protection is suitable for three-phase and, optionally, for single-phase tripping by means of a sophisticated phase selector. It may be blocked during the dead time of single-pole auto-reclose cycles or during pickup of the distance protection.

Tele (pilot) protection for directional ground(earth)-fault protection (ANSI 85-67N)

The directional ground(earth)-fault overcurrent protection can be combined with one of the following teleprotection schemes:

- Directional comparison
- BLOCKING
- UNBLOCKING

The transient blocking function (current reversal guard) is also provided in order to suppress interference signals during tripping of parallel lines.

The pilot functions for distance protection and for ground(earth)-fault protection can use the same signaling channel or two separate and redundant channels.

Backup overcurrent protection (ANSI 50, 50N, 51, 51N)

The 7SD52/53 provides a backup overcurrent protection. Two definite-time stages and one inverse-time stage (IDMTL) are available, separately for phase currents and for the neutral (residual) current. Two operating modes are selectable. The function can run in parallel to the differential

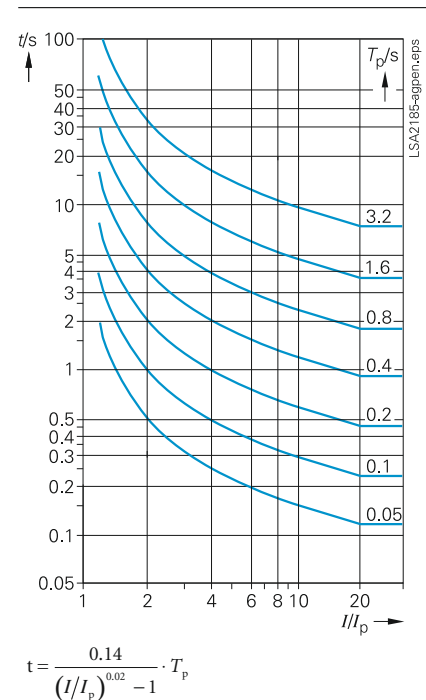


Fig. 7/55 Normal inverse

protection and the distance protection or only during interruption of the protection communication and/or failure of the voltage in the VT secondary circuit (emergency operation). The secondary voltage failure can be detected by the integrated fuse failure monitor or via a binary input from a VT miniature circuit-breaker (VT m.c.b. trip).

The following inverse-time characteristics according to IEC 60255-3 and ANSI/IEEE are provided:

- Inverse
- Short inverse
- Long inverse
- Moderately inverse
- Very inverse
- Extremely inverse
- Definite inverse

STUB bus overcurrent protection (ANSI 50(N)-STUB)

The STUB bus overcurrent protection is a separate definite-time overcurrent stage. It can be activated from a binary input signaling the line isolator (disconnecter) is open. Settings are available for phase and ground (earth)-faults.

Protection functions

Instantaneous high-speed switch-onto-fault overcurrent protection (ANSI 50HS)

Instantaneous tripping is possible when energizing a faulty line. In the event of large fault currents, the high-speed switch-onto-fault overcurrent stage can initiate very fast 3-pole tripping.

With lower fault currents, instantaneous tripping after switch-onto-fault is also possible

- if the breaker positions at the line ends are monitored and connected to the relays. This breaker position monitor offers a high-speed trip during switch-onto-fault conditions.
- with the overreach distance zone Z1B or just with pickup in any zone.

The switch-onto-fault initiation can be detected via the binary input "manual close" or automatically via measurement.

Fault locator

The integrated fault locator calculates the fault impedance and the distance-to-fault. The result is displayed in ohms, miles, kilometers or in percent of the line length. Parallel line and load current compensation is also available.

As an option for a line with two ends, a fault locator function with measurement at both ends of the line is available. Thanks to this feature, accuracy of measurement on long lines under high load conditions and high fault resistances is considerably increased.

Overvoltage protection, undervoltage protection (ANSI 59, 27)

A voltage rise can occur on long lines that are operating at no-load or are only lightly loaded. The 7SD52/53 contains a number of overvoltage measuring elements. Each measuring element is of two-stage design. The following measuring elements are available:

- Phase-to-earth overvoltage
- Phase-to-phase overvoltage
- Zero-sequence overvoltage
The zero-sequence voltage can be connected to the 4th voltage input or be derived from the phase voltages.
- Positive-sequence overvoltage of the local end or calculated for the remote end of the line (compounding).
- Negative-sequence overvoltage

Tripping by the overvoltage measuring elements can be effected either at the local circuit-breaker or at the remote station by means of a transmitted signal.

The 7SD52/53 is fitted, in addition, with three two-stage undervoltage measuring elements:

- Phase-to-earth undervoltage
- Phase-to-phase undervoltage
- Positive-sequence undervoltage

The undervoltage measuring elements can be blocked by means of a minimum current criterion and by means of binary inputs.

Frequency protection (ANSI 81O/U)

Frequency protection can be used for overfrequency and underfrequency protection. Unwanted frequency changes in the network can be detected and the load can be removed at a specified frequency setting. Frequency protection can be used over a wide frequency range (45 to 55, 55 to 65 Hz). There are four elements (selectable as overfrequency or underfrequency) and each element can be delayed separately.

Breaker failure protection (ANSI 50BF)

The 7SD52/53 relay incorporates a two-stage breaker failure protection to detect the failure of tripping command execution, for example due to a defective circuit-breaker. The current detection logic is phase-segregated and can therefore also be used in single-pole tripping schemes. If the fault current is not interrupted after a settable time delay has expired, a retrip command or a busbar trip command is generated. The breaker failure protection can be initiated by all integrated protection functions as well as by external devices via binary input signals.

Auto-reclosure (ANSI 79)

The 7SD52/53 relay is equipped with an auto-reclose function (AR). The function includes several operating modes:

- 3-pole auto-reclosure for all types of faults; different dead times are available depending the type of fault
- 1-pole auto-reclosure for 1-phase faults, no reclosing for multi-phase faults
- 1-pole auto-reclosure for 1-phase faults and for 2-phase faults without earth, no reclosing for multi-phase faults
- 1-pole auto-reclosure for 1-phase and 3-pole auto-reclosing for multi-phase faults
- 1-pole auto-reclosure for 1-phase faults and 2-phase faults without earth and 3-pole auto-reclosure for other faults
- Multiple-shot auto-reclosure
- Interaction with an external device for auto-reclosure via binary inputs and outputs
- Control of the integrated AR function by external protection
- Adaptive auto-reclosure. Only one line end is closed after the dead time. If the fault persists this line end is switched off. Otherwise the other line ends are closed via a command over the communication links. This avoids stress when heavy fault currents are fed from all line ends again.
- Interaction with the internal or an external synchro-check
- Monitoring of the circuit-breaker auxiliary contacts

In addition to the above-mentioned operating modes, several other operating principles can be employed by means of the integrated programmable logic (CFC).

Integration of auto-reclosure in the feeder protection allows evaluation of the line-side voltages. A number of voltage-dependent supplementary functions are thus available:

- DLC
By means of dead-line check, reclosure is effected only when the line is deenergized (prevention of asynchronous breaker closure).
- ADT
The adaptive dead time is employed only if auto-reclosure at the remote station was successful (reduction of stress on equipment).

Protection functions

- **RDT**
Reduced dead time is employed in conjunction with auto-reclosure where no tele-protection method is employed: When faults within the zone extension, but external to the protected line, are switched off for rapid auto-reclosure (RAR), the RDT function decides on the basis of measurement of the return voltage from the remote station which has not tripped whether or not to reduce the dead time.

Synchronism check (ANSI 25)

Where two network sections are switched in by control command or following a 3-pole auto-reclosure, it must be ensured that both network sections are mutually synchronous. For this purpose, a synchronism-check function is provided. After verification of the network synchronism the function releases the CLOSE command. Alternatively, reclosing can be enabled for different criteria, e.g., checking that the busbar or line is not carrying a voltage (dead line or dead bus).

Thermal overload protection (ANSI 49)

A built-in overload protection with a current and thermal alarm stage is provided for the thermal protection of cables and transformers. The trip time characteristics are exponential functions according to IEC 60255-8. The preload is thus considered in the trip times for overloads. An adjustable alarm stage can initiate an alarm before tripping is initiated.

Monitoring and supervision functions

The 7SD52/53 relay provides comprehensive monitoring functions covering both hardware and software. Furthermore, the measured values are continuously checked for plausibility. Therefore the current and voltage transformers are also included in this monitoring system.

Current transformer / Monitoring functions

A broken wire between the CTs and relay inputs under load may lead to maloperation of a differential relay if the load current exceeds the differential setpoint. The 7SD52/53 provides fast broken wire supervision which immediately blocks all line ends if a broken wire condition is measured by a local relay. This avoids maloperation due to broken wire condition. Only the phase where the broken wire is detected is blocked. The other phases remain under differential operation.

Fuse failure monitoring

If any measured voltage is not present due to short-circuit or open circuit in the voltage transformer secondary circuit the distance protection would respond with an unwanted trip due to this loss of voltage. This secondary voltage interruption can be detected by means of the integrated fuse failure monitor. Immediate blocking of distance protection is provided for all types of secondary voltage failures.

Additional measurement supervision functions are

- Symmetry of voltages and currents
- Summation of currents and voltages

Trip circuit supervision (ANSI 74TC)

One or two binary inputs for each circuit-breaker pole can be used for monitoring the circuit-breaker trip coils including the connecting cables. An alarm signal is issued whenever the circuit is interrupted.

Lockout (ANSI 86)

All binary outputs can be stored like LEDs and reset using the LED reset key. The lockout state is also stored in the event of supply voltage failure. Reclosure can only be issued after the lockout state is reset.

Local measured values

The measured values are calculated from the measured current and voltage signals along with the power factor ($\cos \varphi$), the frequency, the active and reactive power. Measured values are displayed as primary or secondary values or in percent of the specific line rated current and voltage. The relay uses a 20 bit high-resolution AD converter and the analog inputs are factory-calibrated, so a high accuracy is reached. The following values are available for measured-value processing:

- Currents $3 \times I_{\text{Phase}}$, $3 I_0$, I_E , I_E sensitive
- Voltages $3 \times V_{\text{Phase-Ground}}$, $3 \times V_{\text{Phase-Phase}}$
 $3 V_0$, V_{en} , V_{SYNC} , V_{COMP}
- Symmetrical components I_1 , I_2 , V_1 , V_2
- Real power P (Watt), reactive power Q (Var), apparent power S (VA)
- Power factor PF ($= \cos \varphi$)
- Frequency f
- Differential and restraint current per phase
- Load impedances with directional indication
 $3 \times R_{\text{Phase-Ground}}$, $X_{\text{Phase-Ground}}$
 $3 \times R_{\text{Phase-Phase}}$, $X_{\text{Phase-Phase}}$
- Long term mean values
 $3 \times I_{\text{Phase}}$; I_1 ; P ; $P+$; $P-$; Q ; $Q+$; $Q-$; S
- Minimum/maximum memory
 $3 \times I_{\text{Phase}}$; I_1 ; $3 \times V_{\text{Phase-Ground}}$
 $3 \times V_{\text{Phase-Phase}}$, $3 V_0$; V_1 ; $P+$; $P-$; $Q+$; $Q-$; S ;
 f ; power factor (+); power factor (-);
from mean values
 $3 \times I_{\text{Phase}}$; I_1 ; P ; Q ; S
- Energy meters
 W_{P+} ; W_{P-} ; W_{Q+} ; W_{Q-}
- Availability of the data connection to the remote line ends per minute and per hour
- Regarding delay time measuring with the GPS-version the absolute time for transmit and receive path is displayed separately.

Limit value monitoring: Limit values are monitored by means of the CFC. Commands can be derived from these limit value indications.

Protection functions

Measured values at remote line ends

Every two seconds the currents and voltages are frozen at the same time at all line ends and transmitted via the communication link. At a local line end, currents and voltages are thus available with their amount and phases (angle) locally and remotely. This allows checking the whole configuration under load conditions. In addition, the differential and restraint currents are also displayed. Important communication measurements, such as delay time or faulty telegrams per minute/hour are also available as measurements. These measured values can be processed with the help of the CFC logic editor.

Commissioning

Special attention has been paid to commissioning. All binary inputs and outputs can be displayed and activated directly. This can simplify the wiring check significantly for the user. The operational and fault events and the fault records are clearly arranged.

Furthermore, all currents and optional voltages and phases are available via communication link at the local relay and are displayed in the relay, with DIGSI 4 or with the Web Monitor.

The operational and fault events and fault records from all line ends share a common time tagging which allows to compare events registered in the different line ends on a common time base.

WEB Monitor – Internet technology simplifies visualization

In addition to the universal DIGSI 4 operating program, the relay contains a WEB server that can be accessed via a telecommunication link using a browser (e.g. Internet Explorer). The advantage of this solution is to operate the unit with standard software tools and at the same time make use of the Intranet/Internet infrastructure. This program shows the protection topology and comprehensive measurements from local and remote line ends. Local and remote measurements are shown as phasors and the breaker positions of each line end are depicted. It is possible to check the correct connection of the current transformers or the correct vector group of a transformer.

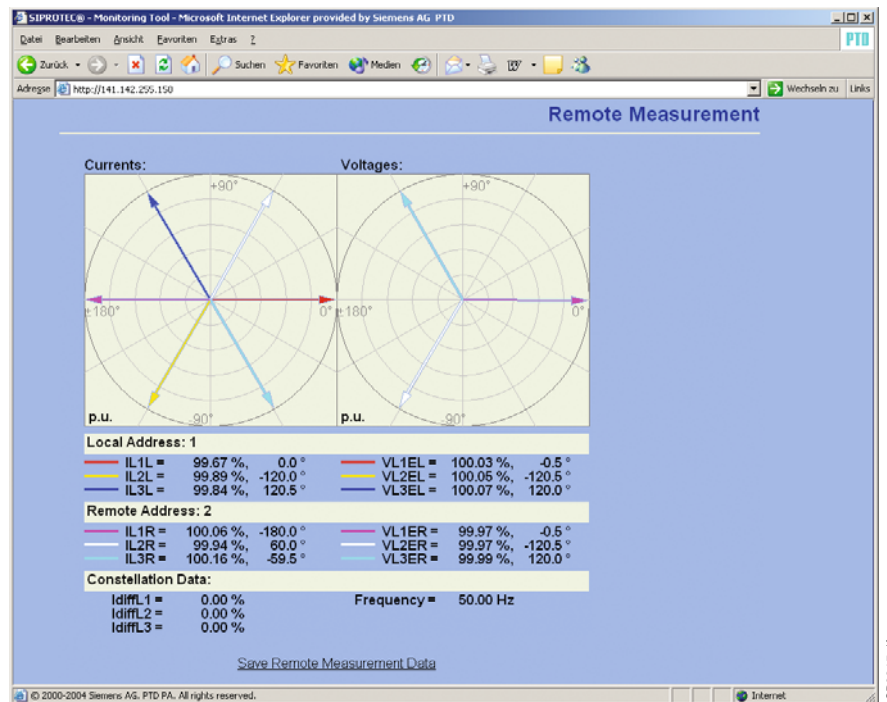


Fig. 7/56
Browser-aided commissioning: Phasor diagram

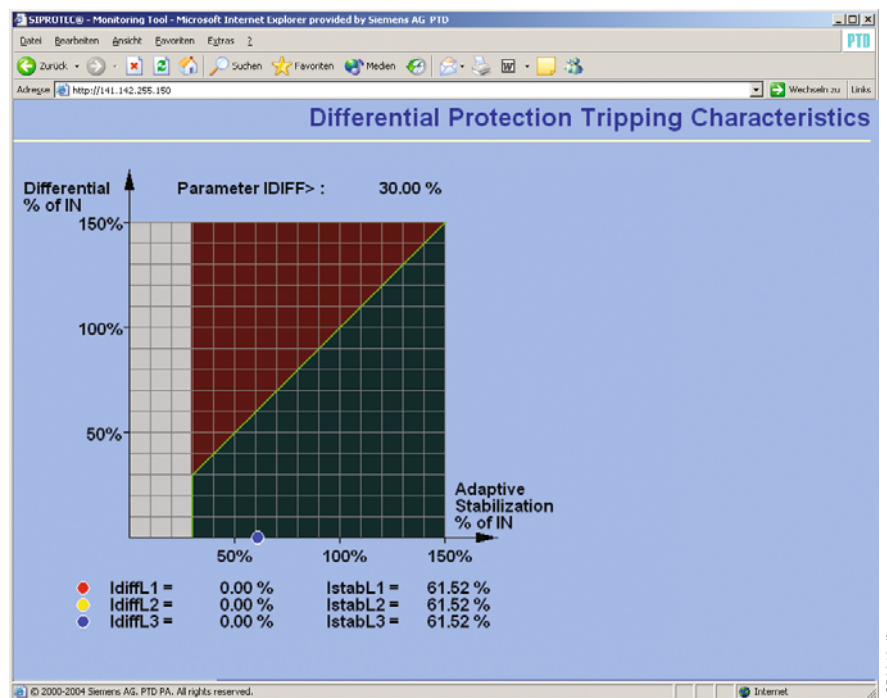


Fig. 7/57
Browser-aided commissioning:
Differential protection tripping characteristic

Stability can be checked by using the operating characteristic as well as the calculated differential and restraint values in the browser windows.

If the distance protection is active, then the valid zone characteristic (quadrilateral/mho) is displayed.

Event log and trip log messages are also available. Remote control can be used, if the local front panel cannot be accessed.

Protection functions

■ Control and automation functions

Control

In addition to the protection functions, the SIPROTEC 4 units also support all control and monitoring functions that are required for operating medium-voltage or high-voltage substations.

The main application is reliable control of switching and other processes.

The status of primary equipment or auxiliary devices can be obtained from auxiliary contacts and communicated via binary inputs. Therefore it is possible to detect and indicate both the OPEN and CLOSED position or a fault or intermediate circuit-breaker or auxiliary contact position.

The switchgear or circuit-breaker can be controlled via:

- integrated operator panel
- binary inputs
- substation control and protection system
- DIGSI 4

Command processing

All the functionality of command processing is offered. This includes the processing of single and double commands with or without feedback, sophisticated monitoring of the control hardware and software, checking of the external process, control actions using functions such as runtime monitoring and automatic command termination after output. Here are some typical applications:

- Single and double commands using 1, 1 plus 1 common or 2 trip contacts
- User-definable bay interlocks
- Operating sequences combining several switching operations such as control of circuit-breakers, disconnectors and earthing switches
- Triggering of switching operations, indications or alarm by combination with existing information

Automation/user-defined logic

With integrated logic, the user can set, via a graphic interface (CFC), specific functions for the automation of switchgear or substation. Functions are activated via function keys, binary input or via communication interface.

Switching authority

Switching authority is determined according to parameters, communication or by key-operated switch (when available).

If a source is set to “LOCAL”, only local switching operations are possible. The following sequence of switching authority is laid down: “LOCAL”; DIGSI PC program, “REMOTE”

Every switching operation and change of breaker position is kept in the status indication memory. The switch command source, switching device, cause (i.e. spontaneous change or command) and result of a switching operation are retained.

Assignment of feedback to command

The positions of the circuit-breaker or switching devices and transformer taps are acquired by feedback. These indication inputs are logically assigned to the corresponding command outputs. The unit can therefore distinguish whether the indication change is a consequence of switching operation or whether it is a spontaneous change of state (intermediate position).

Chatter disable

The chatter disable feature evaluates whether, in a configured period of time, the number of status changes of indication input exceeds a specified figure. If exceeded, the indication input is blocked for a certain period, so that the event list will not record excessive operations.

Filter time

All binary indications can be subjected to a filter time (indication suppression).

Indication filtering and delay

Indications can be filtered or delayed.

Filtering serves to suppress brief changes in potential at the indication input. The indication is passed on only if the indication voltage is still present after a set period of time. In the event of indication delay, there is a wait for a preset time. The information is passed on only if the indication voltage is still present after this time.

Indication derivation

A further indication (or a command) can be derived from an existing indication. Group indications can also be formed. The volume of information to the system interface can thus be reduced and restricted to the most important signals.

Transmission lockout

A data transmission lockout can be activated, so as to prevent transfer of information to the control center during work on a circuit bay.

Test operation

During commissioning, all indications can be passed to an automatic control system for test purposes.

Communication

With respect to communication, particular emphasis has been placed on high levels of flexibility, data integrity and utilization of standards common in energy automation. The design of the communication modules permits interchangeability on the one hand, and on the other hand provides openness for future standards (for example, Industrial Ethernet).

Local PC interface

The PC interface accessible from the front of the unit permits quick access to all parameters and fault event data. Of particular advantage is the use of the DIGSI 4 operating program during commissioning.

Rear-mounted interfaces

Two communication modules located on the rear of the unit incorporate optional equipment complements and readily permit retrofitting. They assure the ability to comply with the requirements of different communication interfaces.

The interfaces make provision for the following applications:

- **Service /modem interface**
By means of the RS232/RS485 or optical interface, it is possible to efficiently operate a number of protection units centrally via DIGSI 4 or standard browser. Remote operation is possible on connection of a modem. This offers the advantage of rapid fault clarification, especially in the case of unmanned power plants. With the optical version, centralized operation can be implemented by means of a star coupler.
- **System interface**
This interface is used to carry out communication with a control or protection and control system and supports a variety of communication protocols and interface designs, depending on the module connected.

Commissioning aid via a standard Web browser

In the case of the 7SD52/53, a PC with a standard browser can be connected to the local PC interface or to the service interface (refer to "Commissioning program"). The relays include a small Web server that sends its HTML pages to the browser via an established dial-up network connection.

Retrofitting: Modules for every type of communication

Communication modules for retrofitting are available for the entire SIPROTEC 4 unit range. These ensure that, where different communication interfaces (electrical or optical) and protocols (IEC 61850 Ethernet, IEC 60870-5-103, PROFIBUS-FMS/-DP, DNP 3.0, DIGSI, etc.) are required, such demands can be met.

Safe bus architecture

- **RS485 bus**
With this data transmission via copper conductors electromagnetic fault influences are largely eliminated by the use of twisted-pair conductors. Upon failure of a unit, the remaining system continues to operate without any disturbances.
- **Fiber-optic double ring circuit**
The fiber-optic double ring circuit is immune to electromagnetic interference. Upon failure of a section between two units, the communication system continues to operate without disturbance.

It is generally impossible to communicate with a unit that has failed. If a unit were to fail, there is no effect on the communication with the rest of the system.

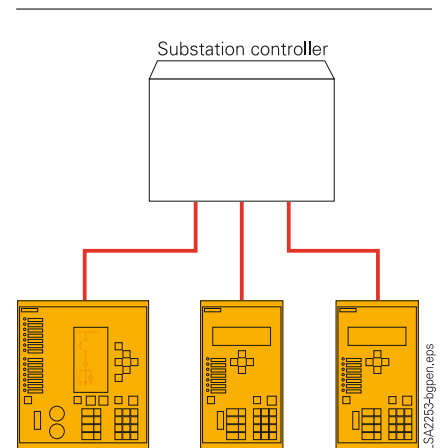


Fig. 7/58
IEC 60870-5-103 star-type RS232 copper conductor connection or fiber-optic connection

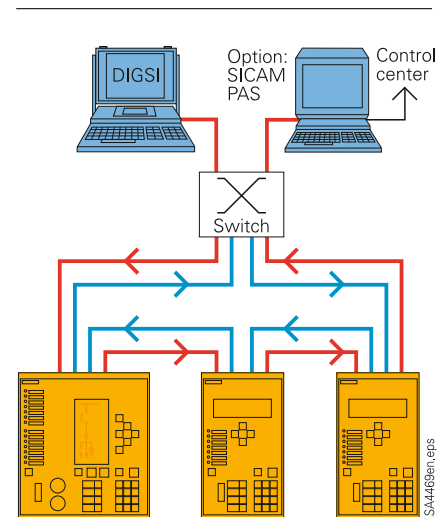


Fig. 7/59
Bus structure for station bus with Ethernet and IEC 61850

Communication

IEC 61850 Ethernet

The Ethernet-based IEC 61850 protocol is the worldwide standard for protection and control systems used by power supply corporations. Siemens was the first manufacturer to support this standard. By means of this protocol, information can also be exchanged directly between bay units so as to set up simple masterless systems for bay and system interlocking. Access to the units via the Ethernet bus is also possible with DIGSI.

IEC 60870-5-103

IEC 60870-5-103 is an internationally standardized protocol for the efficient communication in the protected area. IEC 60870-5-103 is supported by a number of protection device manufacturers and is used worldwide.

PROFIBUS-DP

PROFIBUS-DP is an industry-recognized standard for communications and is supported by a number of PLC and protection device manufacturers.

DNP 3.0

DNP 3.0 (Distributed Network Protocol Version 3) is a messaging-based communication protocol. The SIPROTEC 4 units are fully Level 1 and Level 2 compliant with DNP 3.0. DNP 3.0 is supported by a number of protection device manufacturers.



Fig. 7/60
RS232/RS485 electrical communication module

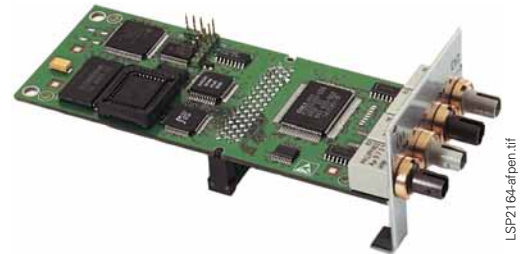


Fig. 7/61
PROFIBUS communication module, optical double-ring

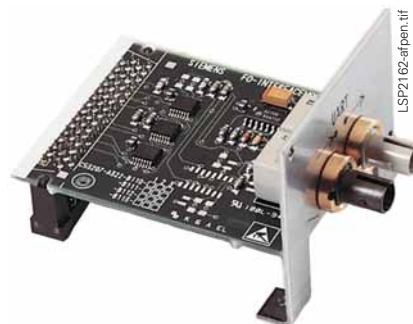


Fig. 7/62
820 nm fiber-optic communication module



Fig. 7/63
Fiber-optic Ethernet communication module for IEC 61850 with integrated Ethernet switch

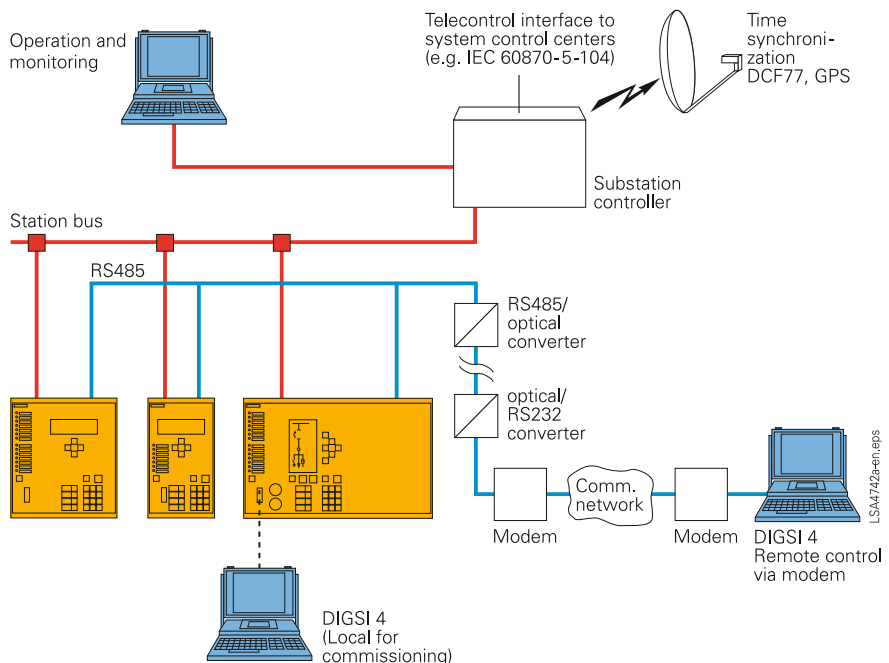


Fig. 7/64
System solution: Communications

Communication

System solutions for protection and station control

Together with the SICAM power automation system, SIPROTEC 4 can be used with PROFIBUS-FMS. Over the low-cost electrical RS485 bus, or interference-free via the optical double ring, the units exchange information with the control system.

Units featuring IEC 60870-5-103 interfaces can be connected to SICAM in parallel via the RS485 bus or radially by fiber-optic link. Through this interface, the system is open for the connection of units of other manufacturers (see Fig. 7/58).

Because of the standardized interfaces, SIPROTEC units can also be integrated into systems of other manufacturers or in SIMATIC. Electrical RS485 or optical interfaces are available. The optimum physical data transfer medium can be chosen thanks to opto-electrical converters. Thus, the RS485 bus allows low-cost wiring in the cubicles and an interference-free optical connection to the master can be established.

For IEC 61850, an interoperable system solution is offered with SICAM PAS. Via the 100 Mbits/s Ethernet bus, the units are linked with PAS electrically or optically to the station PC. The interface is standardized, thus also enabling direct connection of units of other manufacturers to the Ethernet bus. With IEC 61850, however, the units can also be used in other manufacturers' systems (see Fig. 7/59).

Via modem and service interface, the protection engineer has access to the protection devices at all times. This permits remote maintenance and diagnosis (cyclic testing).

Parallel to this, local communication is possible, for example, during a major inspection.

Serial protection data interface (R2R interface)

As an option, the 7SD52/53 provides one or two protection data interfaces to cover two up to six line end applications in ring or chain topology and hot standby communication between two line ends.

In addition to the differential protection function, other protection functions can use this interface to increase selectivity and sensitivity as well as covering advanced applications.

- Fast phase-selective teleprotection signaling for distance protection, optionally with POTT or PUTT schemes
- Two and three-terminal line applications can be implemented without additional logic
- Signaling for directional ground(earth)-fault protection – directional comparison for high-resistance faults in solidly earthed systems
- Echo function
- Inter-close command transfer with the auto-reclosure "Adaptive dead time" (ADT) mode
- 28 remote signals for fast transfer of binary signals

Flexible utilization of the communication channels by means of the programmable CFC logic

The protection data interfaces have different options to cover new and existing communication infrastructures.

- FO5¹⁾, OMA1²⁾ module:
820 nm fiber-optic interface with clock recovery/ST connectors for direct connection with multi-mode FO cable up to 1.5 km for the connection to a communication converter.
- FO6¹⁾, OMA2²⁾ module:
820 nm fiber-optic interface/ST connectors for direct connection up to 3.5 km with multi-mode FO cable.

New fiber-optic interfaces, series FO1x

- FO17¹⁾: For direct connection up to 24 km³⁾, 1300 nm, for mono-mode fiber 9/125 µm, LC-Duplex connector
- FO18¹⁾: For direct connection up to 60 km³⁾, 1300 nm, for mono-mode fiber 9/125 µm, LC-Duplex connector
- FO19¹⁾: For direct connection up to 100 km³⁾, 1550 nm, for mono-mode fiber 9/125 µm, LC-Duplex connector
- FO30: 820 nm fiber-optic interface/ST connectors for direct connection up to 1.5 km and for connections to a IEEE C37.94 multiplexer interface.

The link to a multiplexed communication network is made by separate communication converters (7XV5662). These have a fiber-optic interface with 820 nm and 2 ST connectors to the protection relay. The link to the communication network is optionally an electrical X21 or a G703/-E1/-T1 interface. Furthermore the IEEE C37.94 interface is supported by the FO30 module.

For operation via copper wire communication (pilot wires or twisted telephone pair), a modern communication converter for copper cables is available. This operates with both the two-wire and three-wire copper connections which were used by conventional differential protection systems before. The communication converter for copper cables is designed for 5 kV insulation voltage. An additional 20 kV isolation transformer can extend the field of applications of this technique into ranges with higher insulation voltage requirements. The connection via FO cable to the relay is interference-free. With SIPROTEC 4 and the communication converter for copper cables a digital follow-up technique is available for two-wire protection systems (typical 8 km) and all three-wire protection systems using existing copper communication links.

Different communication converters are listed under "Accessories".

Communication data:

- 32-bit CRC-check according to CCITT and ITU
- Each protection relay possesses a unique relay address
- Continuous communication link supervision: Individual faulty data telegrams do not constitute an immediate danger, if they occur only sporadically. The statistical availability, per minute and hour, of the serial protection data interface can be displayed.
- Supported network interfaces X21/RS422 with 64 or 128 or 512 kbit/s; or G703-64 kbit/s and G703-E1 (2,048 kbit/s) or G703-T1 (1,554 kbit/s).
- Max. channel delay time 0.1 ms to 30 ms (in steps of 0.1 ms) or IEEE C37.94.
- Protocol HDLC

1) For flush-mounting housing.

2) For surface-mounting housing.

3) For surface-mounting housing the internal FO module OMA1 will be delivered together with an external repeater.

Communication

Communication possibilities between relays

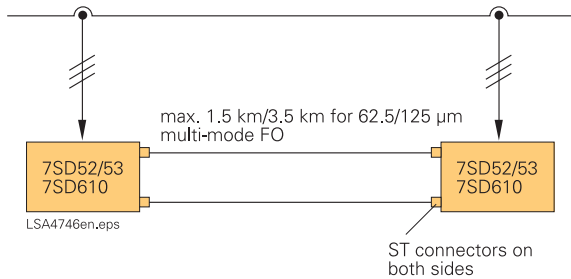


Fig. 7/65
Direct optical link up to 1.5 km/3.5 km, 820 nm

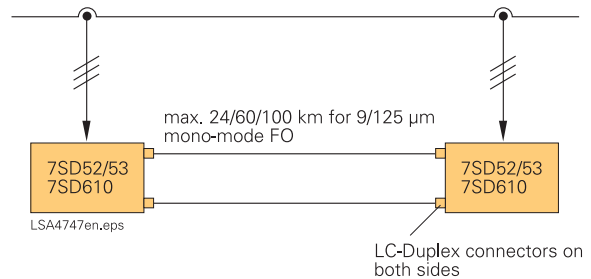


Fig. 7/66
Direct optical link up to 25/60 km with 1300 nm
or up to 100 km with 1550 nm

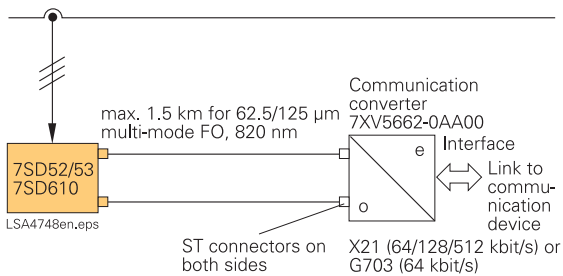


Fig. 7/67
Connection to a communication network CC-XG

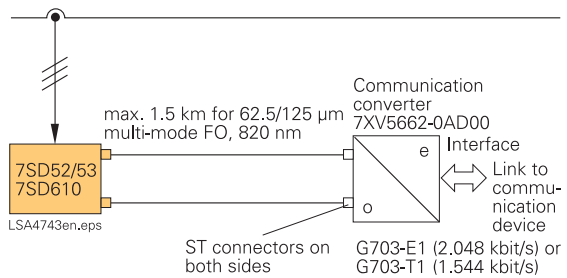


Fig. 7/68
Connection to a communication network CC-2M

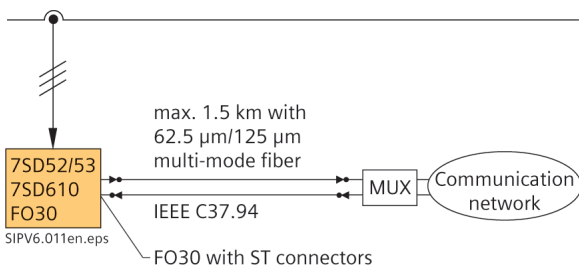


Fig. 7/69
Connection to a communication network via IEEE C37.94

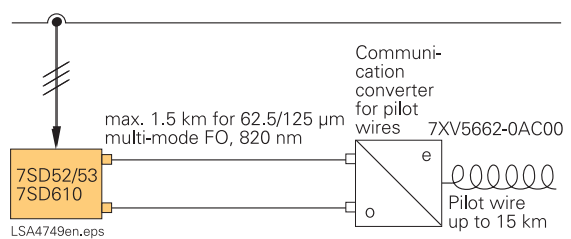


Fig. 7/70
Connection to a pilot wire

Typical connection**Typical connection for current and voltage transformers**

3 phase current transformers with neutral point in the line direction, I_4 connected as summation current transformer ($=3I_0$): Holmgreen circuit

3 voltage transformers, without connection of the broken (open) delta winding on the line side; the $3V_0$ voltage is derived internally.

Note:

Voltage inputs are always available in the relay. But there is no need to connect it to voltage transformers for the differential protection function.

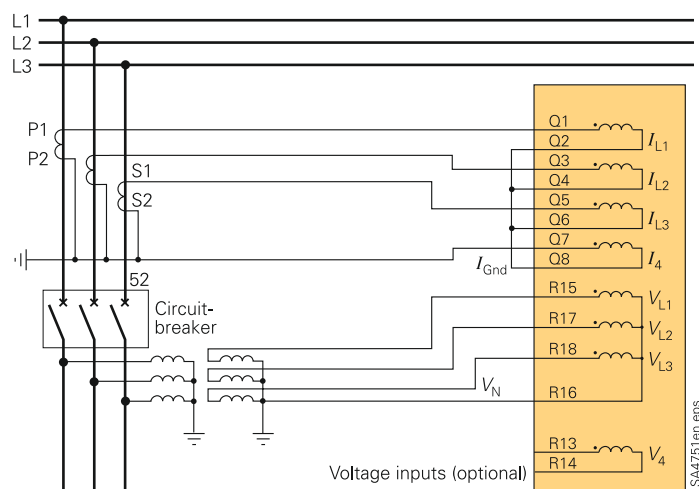


Fig. 7/71

Example of connection for current and voltage transformers

Alternative current measurement

The 3 phase current transformers are connected in the usual manner. The neutral point is in line direction. I_4 is connected to a separate neutral core-balance CT, thus permitting a high sensitive $3I_0$ measurement.

Note: Terminal Q7 of the I_4 transformer must be connected to the terminal of the core-balance CT pointing in the same direction as the neutral point of the phase current transformers (in this case in line direction). The voltage connection is effected in accordance with Fig. 7/71, 7/76 or 7/77.

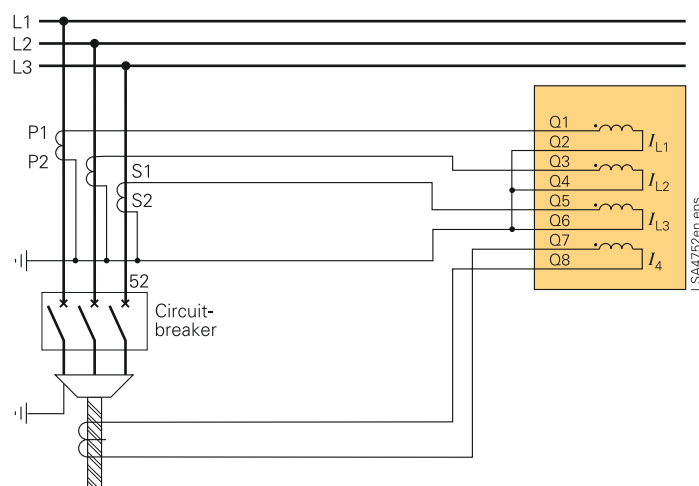


Fig. 7/72

Alternative connection of current transformers for sensitive ground(earth)-current measuring with core-balance current transformers

Typical connection**Alternative current connection**

3 phase current transformers with neutral point in the line direction, I_4 connected to a current transformer in the neutral point of a grounded (earthed) transformer for directional ground(earth)-fault protection. The voltage connection is effected in accordance with Fig. 7/71, 7/76 or 7/77.

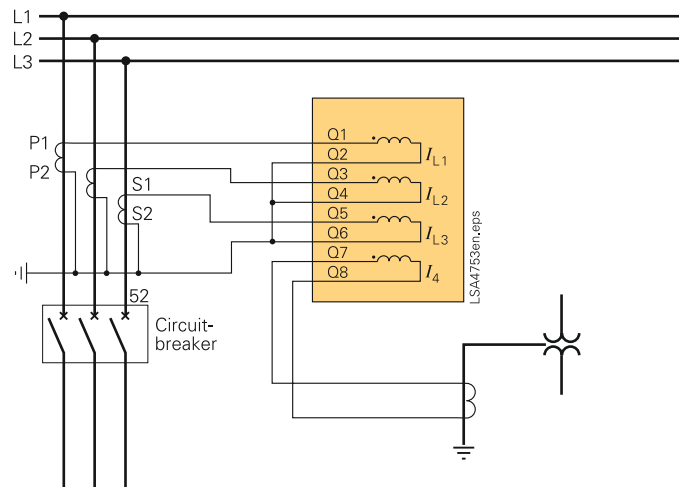


Fig. 7/73 Alternative connection of current transformers for measuring neutral current of a grounded (earthed) power transformer

Alternative current connection

3 phase current transformers with neutral point in the line direction, I_4 connected to the summation current of the parallel line for parallel line compensation on overhead lines. The voltage connection is effected in accordance with Fig. 7/71, 7/76 or 7/77.

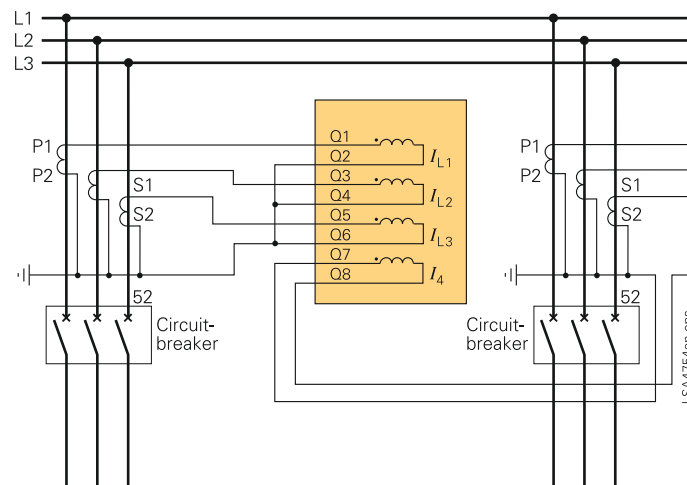


Fig. 7/74 Alternative connection of current transformers for measuring the ground (earth) current of a parallel line

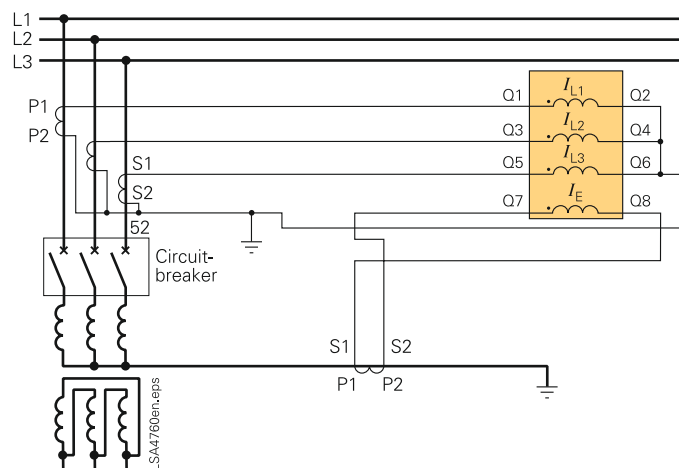


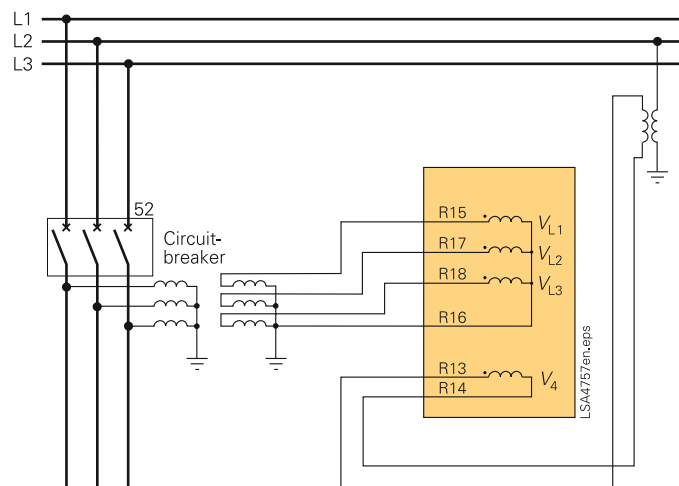
Fig. 7/75 Connection of current transformer with restricted earth-fault protection (REF)

Alternative voltage connection

The diagram shows a three-phase power system. On the left, three horizontal lines represent the main supply busbars, labeled L1, L2, and L3 from top to bottom. Three vertical lines, each with an 'x' symbol, represent the primary windings of a transformer. These are connected to a circuit-breaker labeled '52'. The secondary windings of the transformer are connected to a load block (shaded orange). The load block contains six resistors: R15, R17, and R18 are connected to the L1, L2, and L3 lines respectively; R16 is connected to the neutral line 'n'; R13 and R14 are connected to the 'e' and 'n' lines respectively. The load block also has four voltage measurement points: V_{L1}, V_{L2}, V_{L3}, and V₄. The transformer is grounded at its base, and the neutral line 'n' is also grounded.

Alternative voltage connection

Note: Any phase-to-phase or phase-to-ground(earth) voltage may be employed as the busbar voltage. Parameterization is carried out on the unit. The current connection is effected in accordance with Fig. 7/71, 7/72, 7/73 and 7/74.



Siemens SIP · Edition No. 6

Technical data

General unit data

Analog inputs

Rated frequency	50 or 60 Hz (selectable)
Rated current I_N	1 or 5 A (selectable, controlled by firmware)
Rated voltage	80 to 125 V (selectable)
Power consumption	
In CT circuits with $I_N = 1$ A	Approx. 0.05 VA
In CT circuits with $I_N = 5$ A	Approx. 0.30 VA
In VT circuits	Approx. 0.10 VA
Thermal overload capacity	
In CT circuits	500 A for 1 s 150 A for 10 s 4 x I_N continuous
In VT circuits	230 V, continuous per phase
Dynamic overload capacity	
In CT circuits	1250 A (half cycle)
In the CT circuit for high sensitive earth-fault protection (refer to ordering code)	

Auxiliary voltage

Rated voltage	24 to 48 V DC 60 to 125 V DC ¹⁾ 110 to 250 V DC ¹⁾ and 115 V AC with 50/60 Hz ¹⁾
Permissible tolerance	-20 % to +20 %
Max. superimposed AC voltage (peak-to-peak)	≤ 15 %
Power consumption	
During normal operation	Approx. 8 W
During pickup with all inputs and outputs activated	Approx. 18 W
Bridging time during auxiliary voltage failure V_{aux} 110 V AC/DC	≥ 50 ms

Binary inputs

Quantity	8 or 16 or 24
Function can be assigned	
Minimum permissible voltage	19 or 88 or 176 V DC, bipolar (3 operating ranges)
Range is selectable with jumpers for each binary input	
Maximum permissible voltage	300 V DC
Current consumption, energized	Approx. 1.8 mA

Output relays

Quantity	16 or 24 or 32
Function can be assigned	
Switching capacity	
Make	1000 W /VA
Break	30 VA
Break (for resistive load)	40 W
Break (for $\tau = L/R \leq 50$ ms)	25 VA
Switching voltage	250 V
Permissible current	30 A for 0.5 s 5 A continuous

1) Ranges are settable by means of jumpers.

LEDs

	Quantity
RUN (green)	1
ERROR (red)	1
Indication (red), function can be assigned	14

Unit design

Housing 7XP20 1/2 x 19" or 1/1 x 19"	See dimension drawings, part 15
Degree of protection acc. to EN 60529	
Surface-mounting housing	IP 51
Flush-mounting housing	
Rear	IP 51
Front	IP 51
For the terminals	IP 2x with cover cap
Weight	
Flush-mounting housing	
1/2 x 19"	6 kg
1/1 x 19"	10 kg
Surface-mounting housing	
1/2 x 19"	11 kg
1/1 x 19"	19 kg

Serial interfaces (front of unit)

Operating interface 1 for DIGSI 4 or browser

Connection	Front panel, non-isolated, RS232, 9-pin subminiature connector
Baud rate	4800 to 115200 baud

Time synchronization (rear of unit)

IRIG-B/DCF77/SCADA or 1 sec pulse from GPS (format IRIG-B000)

Connection	9-pin subminiature connector (SUB-D)
Voltage levels	5 or 12 or 24 V
Dielectric test	500 V/50 Hz

Service interface (operating interface 2) for DIGSI 4 / modem / service

Isolated RS232/RS485	9-pin subminiature connector
Dielectric test	500 V/50 Hz
Distance for RS232	Max. 15 m
Distance for RS485, depends on the baud rate	Max. 1000 m
Fiber-optic	Integrated ST connector
Optical wavelength	$\lambda = 820$ nm
Permissible attenuation	Max. 8 dB for glass-fiber 62.5/125 μ m
Distance	Max. 1.5 km

System interface

(refer to ordering code)	IEC 61850 Ethernet IEC 60870-5-103 PROFIBUS-FMS PROFIBUS-DP DNP 3.0
Isolated RS232/RS485	9-pin subminiature connector
Baud rate	4800 to 38400 baud
Dielectric test	500 V/50 Hz
Distance for RS232	Max. 15 m
Distance for RS485	Max. 1000 m

Technical data

System interface, continued

PROFIBUS RS485	
Dielectric test	500 V/50 Hz
Baud rate	Max. 12 Mbaud
Distance	1 km at 93.75 kB; 100 m at 12 MB
PROFIBUS fiber-optic ²⁾	
Only for flush-mounting housing	ST connector
For surface-mounting housing	Optical interface with OLM ²⁾
Baud rate	Max. 1.5 Mbaud
Optical wavelength	$\lambda = 820$ nm
Permissible attenuation	Max. 8 dB for glass-fiber 62.5/125 μ m
Distance	500 kB/s 1.6 km, 1500 kB/s 530 m

Protection data interface (R2R interface)

FO5 ¹⁾ , OMA1 ²⁾ : Fiber-optic interface with clock recovery for direct connection up to 1.5 km or for connection to a communication converter, 820 nm	For multi-mode fiber 62.5/125 μ m, ST connectors Permissible fiber attenuation 8 dB
FO6 ¹⁾ , OMA2 ²⁾ : Fiber-optic interface for direct connection up to 3.5 km, 820 nm	For multi-mode fiber 62.5/125 μ m, ST connectors Permissible fiber attenuation 16 dB

New fiber-optic interfaces, series FO1x

FO17 ¹⁾ : for direct connection up to 24 km ³⁾ , 1300 nm	For mono-mode fiber 9/125 μ m, LC-Duplex connector Permissible fiber attenuation 13 dB
FO18 ¹⁾ : for direct connection up to 60 km ³⁾ , 1300 nm	For mono-mode fiber 9/125 μ m, LC-Duplex connector Permissible fiber attenuation 29 dB
FO19 ¹⁾ : for direct connection up to 100 km ³⁾ , 1550 nm	For mono-mode fiber 9/125 μ m, LC-Duplex connector Permissible fiber attenuation 29 dB

Relay communication equipment

External communication converter 7XV5662-0AA00 for communication networks X21/G703-64 kbit/s

External communication converter to interface between the relays, optical 820 nm interface and the X21 (RS422) G703-64 kbit/s interface of a communication device	
X21/G703, RS422 selectable by jumpers. Baud rate selectable by jumpers	
Input: fiber-optic 820 nm with clock recovery	Max. 1.5 km with 62.5/125 μ m multi-mode FO cable to device side
Output: X21 (RS422) electrical interface on communication device	64/128/512 kbit (selectable by jumper) max. 800 m, 15-pin connector
G703-64 kbit/s electrical interface on communication device	64 kbit/s, max. 800 m, screw-type terminal

External communication converter 7XV5662-0AD00 for communication networks with G703-E1 or G703-T1

External communication converter to interface between the relays, optical 820 nm interface and G703-E1 or G703-T1 interface of a communication network.	
Inputs: 2 fiber-optic inputs 820 nm, 1RS232 input	Max. 1.5 km with 62.5/125 μ m multi-mode 1 FO cable to device side
Output: G703.5 G703.6	E1: 2,048 kbit/s T1: 1,554 kbit/s
Electrical interface on communication network	max. 800 m, screw-type terminal

External communication converter 7XV5662-0AC00 for pilot wires

External communication converter to interface between relays, optical 820 nm interface and a pilot wire or twisted telephone pair.	
Typical distance	15 km
Fiber-optic 820 nm with clock recovery	Max. 1.5 km with 62.5/125 μ m multi-mode FO cable
Pilot wire	Screw-type terminal 5 kV isolated
Permissible time delay (duration of data transmission)	
Delay of telegrams due to transmission for one unit to the other. Delay is constantly measured and adjusted	Max. 30 ms per transmission path Permissible max. value can be selected

Electrical tests

Specifications

Standards	IEC 60255 (product standards) ANSI/IEEE C37.90.0/.1/.2 UL 508 For further standards see "Individual functions"
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Insulation tests

Standards	IEC 60255-5
Voltage test (100 % test)	
All circuits except for auxiliary supply, binary inputs and communication interfaces	2.5 kV (r.m.s.), 50/60 Hz
Auxiliary voltage and binary inputs (100 % test)	3.5 kV DC
RS485/RS232 rear side communication interfaces and time synchronization interface (100 % test)	500 V (r.m.s.), 50/60 Hz
Impulse voltage test (type test)	
All circuits except for communication interfaces and time synchronization interface, class III	5 kV (peak); 1.2/50 μ s; 0.5 J 3 positive and 3 negative impulses at intervals of 5 s

EMC tests for noise immunity; type tests

Standards	IEC 60255-6, IEC 60255-22 (product standards) (type tests) EN 50082-2 (generic standard) DIN 57435 part 303
High frequency test IEC 60255-22-1, class III and VDE 0435 part 303, class III	2.5 kV (peak); 1 MHz; $\tau = 15$ ms; 400 surges per s; test duration 2 s
Electrostatic discharge IEC 60255-22-2, class IV EN 61000-4-2, class IV	8 kV contact discharge; 15 kV air discharge; both polarities; 150 pF; $R_i = 330 \Omega$
Irradiation with RF field, non-modulated IEC 60255-22-3 (report), class III	10 V/m; 27 to 500 MHz
Irradiation with RF field, amplitude-modulated IEC 61000-4-3, class III	10 V/m; 80 to 1000 MHz; 80 % AM; 1 kHz

- 1) For flush-mounting housing.
- 2) For surface-mounting housing.
- 3) For surface-mounting housing the internal FO module OMA1 will be delivered together with an external repeater.

Technical data

Irradiation with RF field, pulse-modulated IEC 61000-4-3/ ENV 50204, class III	10 V/m; 900 MHz; repetition frequency 200 Hz; duty cycle 50 %
Fast transients, bursts IEC 60255-22-4 and IEC 61000-4-4, class IV	4 kV; 5/50 ns; 5 kHz; burst length = 15 ms; repetition rate 300 ms; both polarities; $R_i = 50 \Omega$; test duration 1 min
High-energy surge voltages (SURGE) IEC 61000-4-5, installation class III Auxiliary supply	Common mode: 2 kV, 12 Ω , 9 μ F Differential mode: 1 kV; 2 Ω , 18 μ F
Measurements inputs, binary inputs, binary outputs	Common mode: 2 kV, 42 Ω , 0.5 μ F Differential mode: 1 kV; 42 Ω , 0.5 μ F
Line-conducted HF, amplitude-modulated, IEC 61000-4-6, class III	10 V; 150 kHz to 80 MHz; 80 % AM; 1 kHz
Magnetic field with power frequency IEC 61000-4-8, class IV; IEC 60255-6	30 A/m continuous; 300 A/m for 3 s; 50 Hz; 0.5 mT; 50 MHz
Oscillatory surge withstand capability ANSI/IEEE C37.90.1	2.5 to 3 kV (peak); 1 to 1.5 MHz Damped wave; 50 surges per second; Duration 2 s; $R_i = 150 \Omega$ to 200 Ω
Fast transient surge withstand capability, ANSI/IEEE C37.90.1	4 to 5 kV; 10/150 ns; 50 surges per second; both polarities; duration 2 s; $R_i = 80 \Omega$
Radiated electromagnetic interference, IEEE C37.90.2	35 V/m; 25 to 1000 MHz amplitude and pulse-modulated
Damped oscillations IEC 60894, IEC 61000-4-12	2.5 kV (peak value), polarity alternating 100 kHz 1, 10 and 50 MHz, $R_i = 200 \Omega$
EMC tests for interference emission; type tests	
Standard	EN 50081-* (generic standard)
Conducted interference voltage on lines, only auxiliary supply, IEC-CISPR 22	150 kHz to 30 MHz Limit class B
Radio interference field strength IEC-CISPR 22	30 to 1000 MHz Limit class B

Mechanical dynamic tests

Vibration, shock stress and seismic vibration

<u>During operation</u>	
Standards	IEC 60255-21 and IEC 60068-2
Vibration IEC 60255-21-1, class 2 IEC 60068-2-6	Sinusoidal 10 to 60 Hz: ± 0.075 mm amplitude; 60 to 150 Hz: 1 g acceleration frequency sweep 1 octave/min 20 cycles in 3 orthogonal axes
Shock IEC 60255-21-2, class 1 IEC 60068-2-27	Half-sinusoidal acceleration 5 g, duration 11 ms, 3 shocks each in both directions of the 3 axes
Seismic vibration IEC 60255-21-2, class 1 IEC 60068-3-3	Sinusoidal 1 to 8 Hz: ± 3.5 mm amplitude (horizontal axis), 1 to 8 Hz: ± 1.5 mm amplitude (vertical axis), 8 to 35 Hz: 1 g acceleration (horizontal axis), 8 to 35 Hz: 0.5 g acceleration (vertical axis), frequency sweep 1 octave/min 1 cycle in 3 orthogonal axes
1) Ordering option with high-speed contacts required.	

<u>During transport</u>	
Standards	IEC 60255-21 and IEC 60068-2
Vibration IEC 60255-21-1, class 2 IEC 60255-2-6	Sinusoidal 5 to 8 Hz: ± 7.5 mm amplitude; 8 to 150 Hz: 2 g acceleration frequency sweep 1 octave/min 20 cycles in 3 orthogonal axes
Shock IEC 60255-21-2, class 1 IEC 60068-2-27	Half-sinusoidal Acceleration 15 g, duration 11 ms, 3 shocks each in both directions of the 3 axes
Continuous shock IEC 60255-21-2, class 1 IEC 60068-2-29	Half-sinusoidal Acceleration 10 g, duration 16 ms, 1000 shocks each in both directions of the 3 axes

Climatic stress tests

Temperatures

Type-tested acc. to IEC 60068-2-1 and -2, test Bd, for 16 h	-25 °C to +85 °C / -13 °F to +185 °F
Temporarily permissible operating temperature, tested for 96 h	-20 °C to +70 °C / -4 °F to +158 °F
Recommended permanent operating temperature acc. to IEC 60255-6 (Legibility of display may be impaired above +55 °C / +131 °F)	-5 °C to +55 °C / +25 °F to +131 °F
– Limiting temperature during permanent storage	-25 °C to +55 °C / -13 °F to 131 °F
– Limiting temperature during transport	-25 °C to +70 °C / -13 °F to +158 °F

Humidity

Permissible humidity stress It is recommended to arrange the units in such a way, that they are not exposed to direct sunlight or pronounced temperature changes that could cause condensation.	Yearly average ≤ 75 % relative humidity; on 56 days in the year up to 93 % relative humidity; condensation is not permitted
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Functions

Differential protection (ANSI 87L, 87T)

Sensitive normal trip stage $I_{Diff>}$

Setting range of $I_{Diff>}$ secondary 1 A secondary 5 A	0.1 to 20 A (step 0.1) 0.5 to 100 A
Tripping time (three line ends) $I_{Diff>} > 2.5 \times I_{Diff>}$ (setting)	50 Hz Min. 27 ms Typ. 29 ms 60 Hz Min. 24 ms Typ. 26 ms

Delay time of $I_{Diff>}$ trip stage

Delay time	0 to 60 s (step 0.01 s)
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Capacitive current load compensation

Restraint ratio $I_{C\text{ STAB}} / I_{CN}$	2 to 4 (steps 0.1)
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High-set fast trip stage $I_{Diff>>}$

Setting range $I_{Diff>>}$ secondary 1 A secondary 5 A	0.8 to 100 A (step 0.1) 4 to 500 A (step 0.5)
Tripping time (three line ends) $I_{Diff>>} \geq 2.5 \times I_{Diff>>}$ (setting)	Min. 9 ms ¹⁾ Typ. 12 ms ¹⁾

Technical data

Vector group adaptation with transformers in the differential zone

Adaptation of connection symbol	0 to 11 (x 30 °) (step 1)
Neutral point connection	Grounded (earthed) or not grounded (earthed) (for each winding)

Inrush restraint

Restraint ratio 2 nd harmonic I_{2N}/I_{1N}	10 % to 45 % (step 1 %)
Max. current for restraint	1.1 A to 25 A ¹⁾ (step 0.1 A)
Crossblock function	Can be switched on and off
Max. operative time for crossblock $T_{oper\ crossblk}$	0 to 60 s (step 0.01 s) or deactivated (operating up to release)

Distance protection (ANSI 21, 21N)

Distance protection zones	6, 1 of which as controlled zone, all zones can be set forward or/and reverse
Time stages for tripping delay	6 for multi-phase faults 3 for single-phase faults
Setting range	0 to 30 s or deactivated (steps 0.01 s)
Characteristic	(refer to ordering code)
Selectable separately for phase and ground (earth) faults	quadrilateral and/or Mho (only impedance pickup)
Types of pickup	Overcurrent pickup ($I>$); Voltage-dependent overcurrent pickup ($V</I>$); Voltage-dependent and phase angle-dependent overcurrent pickup ($V</I>/\varphi>$); Impedance pickup ($Z<$)
Types of tripping	Three-pole for all types of faults; Single-pole for single-phase faults / otherwise three-pole; Single-pole for single-phase faults and two-pole phase-to-phase faults / otherwise three-pole
Time range	0 to 30 s (step 0.01 s) or deactivated
Line angle φ_L	30 ° to 89 ° (step 1 °)
Inclination angle for quadrilateral characteristic	30° to 90° (step 1°)
Quadrilateral reactance reach X	0.05 to 600 $\Omega_{(1A)}$ / 0.01 to 120 $\Omega_{(5A)}$ (step 0.001 Ω)
Quadrilateral resistance reach R for phase-to-phase faults and phase-to-ground(earth) faults	0.05 to 600 $\Omega_{(1A)}$ / 0.01 to 120 $\Omega_{(5A)}$ (step 0.001 Ω)
Mho impedance reach ZR	0.05 to 200 $\Omega_{(1A)}$ / 0.01 to 40 $\Omega_{(5A)}$ (step 0.01 Ω)
Minimum phase current I	0.05 to 4 A _(1A) / 0.25 to 20 A _(5A) (step 0.01 A)
Overcurrent pickup $I>>$ (for $I>$, $V</I>$, $V</I>/\varphi>$)	0.25 to 10 A _(1A) / 1.25 to 50 A _(5A) (step 0.01 A)
Minimum current pickup $I>$ (for $V</I>$, $V</I>/\varphi>$ and $Z<$)	0.05 to 4 A _(1A) / 0.25 to 20 A _(5A) (step 0.01 A)
Minimum current pickup $I_{\varphi>}$ (for $V</I>$, $V</I>/\varphi>$)	0.1 to 8 A _(1A) / 0.5 to 40 A _(5A) (step 0.01 A)
Undervoltage pickup (for $V</I>$ and $V</I>/\varphi>$)	
$V_{ph-e<}$	20 to 70 V (step 1 V)
$V_{ph-ph<}$	40 to 130 V (step 1 V)
Load angle pickup (for $V</I>/\varphi>$)	
Load angle φ	30 ° to 80 °
Load angle φ	90 ° to 120 °

Ground(earth)-fault pickup Neutral (residual) current $3I_0$ (Ground current)	0.05 to 4 A _(1A) / 0.25 to 20 A _(5A) (step 0.01 A)
Zero-sequence voltage $3V_0>$ for earthed networks for resonant-earthed networks	1 to 100 V (step 1 V) or deactivated 10 to 200 V (step 1 V)
Zero-sequence compensation Selectable input formats	R_E/R_L and X_E/X_L k_0 and $\varphi(k_0)$
Separately selectable for zones	Z1 higher zones (Z1B, Z2 to Z5)
R_E/R_L and X_E/X_L	-0.33 to 7 (step 0.01)
k_0	0 to 4 (step 0.001)
$\varphi(k_0)$	-135 to 135 ° (step 0.01 °)
Parallel line mutual compensation R_M/R_L and X_M/X_L	(refer to ordering code) 0.00 to 8 (step 0.01)
Phase reference on double earth-faults in resonant-earthed/non-earthed network	Phase preference or no preference (selectable)
Load encroachment Minimum load resistance	0.10 to 600 $\Omega_{(1A)}$ / 0.02 to 120 $\Omega_{(5A)}$ (step 0.001 Ω) or deactivated
Maximum load angle	20 to 60 ° (step 1 °)
Directional decision for all types of faults	With sound phase polarization and/or voltage memory
Directional sensitivity	Dynamically unlimited
Tolerances	For sinusoidal quantities
Impedances (in conformity with DIN 57435, Part 303)	$\left \frac{\Delta X}{X} \right \leq 5\% \text{ for } 30^\circ \leq \varphi_{SC} \leq 90^\circ$
	$\left \frac{\Delta R}{R} \right \leq 5\% \text{ for } 0^\circ \leq \varphi_{SC} \leq 60^\circ$
	$\left \frac{\Delta Z}{Z} \right \leq 5\% \text{ for } -30^\circ \leq (\varphi_{SC} - \varphi_{line}) \leq +30^\circ$
Response values (in conformity with DIN 57435, Part 303) V and I Angle (φ)	$\leq 5\%$ of setting value $\leq 3^\circ$
Timer tolerance	$\pm 1\%$ of set value or 10 ms
Operating times	
Minimum trip time with fast relays	Approx. 17 ms at 50 Hz Approx. 15 ms at 60 Hz
Minimum trip time with high-speed relays	Approx. 12 ms at 50 Hz Approx. 10 ms at 60 Hz
Reset time	Approx. 30 ms

1) Secondary data for $I_N = 1$ A; with $I_N = 5$ A the values must be multiplied.

Technical data

Power swing detection (ANSI 68, 68T)

Power swing detection principle	Measurement of the rate of impedance vector change and monitoring of the vector path
Max. detectable power swing frequency	Approx. 7 Hz
Operating modes	Power swing blocking and/or power swing tripping (out-of-step tripping)
Power swing blocking programs	All zones blocked Z1/Z1B blocked Z2 to Z5 blocked Z1, Z1B, Z2 blocked
Detection of faults during power swing blocking	Reset of power swing blocking for all types of faults

Tele (pilot) protection for distance protection (ANSI 85-21)

Modes of operation	PUTT (Z1B acceleration); DUTT PUTT (acceleration with pickup); POTT; Directional comparison; Reverse interlocking Pilot-wire comparison; Unblocking; Blocking
Additional functions	Echo function (refer to weak-infeed function) Transient blocking for schemes with measuring range extension
Transmission and reception signals	Phase-selective signals available for maximum selectivity with single-pole tripping; signals for 2 and 3-end- lines

Direct transfer trip (DTT)

Direct phase-selective tripping via binary input	Alternatively with or without auto-reclosure
Trip time delay	0 to 30 s (step 0.01 s) or deactivated
Timer tolerance	± 1 % of setting value or 10 ms

Backup overcurrent protection (ANSI 50N, 51N)

Operating modes	Active only with loss of data connection and voltage or always active
Characteristics	3 definite-time stages / 1 inverse-time stage

Definite-time stage (ANSI 50, 50N)

Pickup definite time stage 1, phase current	0.1 to 25 A _(1A) / 0.5 to 125 A _(5A) (step 0.01 A) or deactivated
Pickup definite-time stage 1, neutral (residual) current	0.5 to 25 A _(1A) / 0.25 to 125 A _(5A) (step 0.01 A) or deactivated
Pickup definite-time stage 2, phase current	0.1 to 25 A _(1A) / 0.5 to 125 A _(5A) (step 0.01 A) or deactivated
Pickup definite-time stage 2, neutral (residual) current	0.05 to 25 A _(1A) / 0.25 to 125 A _(5A) (step 0.01 A) or deactivated
Pickup definite-time stage 3, phase current	0.1 to 25 A _(1A) / 0.5 to 125 A _(5A) (step 0.01 A) or deactivated
Pickup definite-time stage 3, neutral (residual) current	0.05 to 25 A _(1A) / 0.25 to 125 A _(5A) (step 0.01 A) or deactivated
Time delay for definite-time stages	0 to 30 s, (step 0.01 s) or deactivated
Tolerances	
Current pickup	≤ 3 % of set value or 1 % of I _N
Delay times	± 1 % of set value or 10 ms
Operating time	Approx. 25 ms

Inverse-time stage (ANSI 51, 51N)

Phase current pickup	0.1 to 4 A _(1A) / 0.5 to 20 A _(5A) (step 0.01 A) or deactivated
Neutral (residual) current pickup	0.05 to 4 A _(1A) / 0.25 to 20 A _(5A) (step 0.01 A) or deactivated
<u>Characteristics</u>	
Characteristics according to IEC 60255-3	Normal inverse Very inverse Extremely inverse Long time inverse
Time multiplier	T _p = 0.05 to 3 s (step 0.01 s) or deactivated
Pickup threshold	Approx. 1.1 x I / I _p
Reset threshold	Approx. 1.05 x I / I _p
Tolerances	
Operating time for 2 ≤ I/I _p ≤ 20	≤ 5 % of setpoint ± 15 ms
Characteristics according to ANSI/IEEE	Inverse Short inverse Long inverse Moderately inverse Very inverse Extremely inverse Definite inverse
Time dial	0.5 to 15 (step 0.01) or deactivated
Pickup threshold	Approx. 1.1 x M
Reset threshold	Approx. 1.05 x M
Tolerances	
Operating time for 2 ≤ M ≤ 20	≤ 5 % of setpoint ± 15 ms

Instantaneous high-speed switch-onto-fault overcurrent protection (ANSI 50HS)

Operating mode	Active only after c.b. closing; instantaneous trip after pickup
Characteristic	2 definite-time stages
Pickup current I >>>	0.1 to 15 A _(1A) / 0.5 to 75 A _(5A) (step 0.01 A) or deactivated
Pickup current I >>>>	1 to 25 A _(1A) / 5 to 125 A _(5A) (step 0.01 A) or deactivated
Reset ratio	Approx. 0.95
Tolerances	< 3 % of set value or 1 % of I _N

Directional ground (earth)-fault overcurrent protection for high-resistance faults in systems with earthed star point (ANSI 50N, 51N, 67N)

Characteristic	3 definite-time stages / 1 inverse-time stage or 4 definite-time stages or 3 definite-time stages / 1 V _{0invers.} stage
Phase selector	Permits 1-pole tripping for single-phase faults or 3-pole tripping for multi-phase faults
Inrush restraint	Selectable for every stage
Instantaneous trip after switch-onto-fault	Selectable for every stage
Influence of harmonics	
Stages 1 and 2 (I>>> and I>>)	3 rd and higher harmonics are completely suppressed by digital filtering
Stages 3 and 4 (I> and inverse 4 th stage)	2 nd and higher harmonics are completely suppressed by digital filtering

Technical data

Definite-time stage (ANSI 50N)

Pickup value $3I_{0>>>}$	0.5 to 25 A _(1A) / 2.5 to 125 A _(5A) (step 0.01 A)
Pickup value $3I_{0>>}$	0.2 to 25 A _(1A) / 1 to 125 A _(5A) (step 0.01 A)
Pickup value $3I_{0>}$	0.05 to 25 A _(1A) / 0.25 to 125 A _(5A) (step 0.01 A) Neutral (residual) current transformer with normal sensitivity (refer to ordering data, position 7); 0.003 to 25 A _(1A) / 0.015 to 125 A _(5A) (step 0.001 A) Neutral (residual) current transformer with high sensitivity (refer to ordering data, position 7)
Pickup value $3I_{0, 4^{th}}$ stage	0.05 to 25 A _(1A) / 0.25 to 125 A _(5A) (step 0.01 A) Neutral (residual) current transformer with normal sensitivity (refer to ordering data, position 7); 0.003 to 25 A _(1A) / 0.015 to 125 A _(5A) (step 0.001 A) Neutral (residual) current transformer with high sensitivity (refer to ordering data, position 7)
Time delay for definite-time stages	0 to 30 s (step 0.01 s) or deactivated
Tolerances	
Current pickup	≤ 3 % of setting value or 1 % I_N
Delay times	1 % of setting value or 10 ms
Command / pickup times $3I_{0>>>}$ and $3I_{0>>}$	Approx. 30 ms
Command / pickup times $3I_{0>}$ and $3I_{0, 4^{th}}$ stage	Approx. 40 ms

Inverse-time stage (ANSI 51N)

Ground (earth)-current pickup $3I_{0P}$	0.05 to 4 A _(1A) / 0.25 to 20 A _(5A) (step 0.01 A) Neutral (residual) current transformer with normal sensitivity (refer to ordering data, position 7) 0.003 to 4 A _(1A) / 0.015 to 20 A _(5A) (step 0.001 A) Neutral (residual) current transformer with high sensitivity (refer to ordering data, position 7)
Tripping characteristics acc. to IEC 60255-3	Normal inverse; very inverse; extremely inverse; long inverse
ANSI/IEEE tripping characteristic (not for region DE, refer to ordering data, position 10)	Inverse; short inverse; long inverse; moderately inverse; very inverse; extremely inverse; definite inverse
Inverse logarithmic tripping characteristics (not for regions DE and US, refer to ordering data, position 10)	$t = T_{3I0Pmax} - T_{3I0P} \cdot \ln \frac{3I0}{3I0_P}$
Pickup threshold	1.1 to 4.0 x I/I_P (step 0.1 s)
Time multiplier for IEC T characteristics	$T_P = 0.05$ to 3 s (step 0.01 s)
Time multiplier for ANSI D characteristics	$D_{10P} = 0.5$ to 15 s (step 0.01 s)
Pickup threshold	Approx. 1.1 x I/I_P (ANSI: $I/I_P = M$)
Inverse logarithmic pickup threshold	1.1 to 4.0 x I/I_{0P} (step 0.1)
Reset threshold	Approx. 1.05 x I/I_{0P} (ANSI: $I/I_P = M$)
Tolerance	
Operating time for $2 \leq I/I_P \leq 20$	≤ 5 % of setpoint ± 15 ms

Zero-sequence voltage protection $V_{0inverse}$

Tripping characteristic	$t = \frac{2 \text{ s}}{\frac{V_0}{4} - V_{0inv \min}}$
Direction decision (ANSI 67N)	
Measured signals for direction decision	$3I_0$ and $3V_0$ or $3I_0$ and $3V_0$ and I_Y (star point current of an earthed power transformer) or $3I_2$ and $3V_2$ (negative-sequence system) or zero-sequence power S_0 or automatic selection of zero-sequence or negative-sequence quantities dependent on the magnitude of the component voltages
Min. zero-sequence voltage $3V_0$	0.5 to 10 V (step 0.1 V)
Min. current I_Y (of grounded (earthed) transformers)	0.05 to 1 A _(1A) / 0.25 to 5 A _(5A) (step 0.01 A)
Min. negative-sequence voltage $3V_2$	0.5 to 10 V (step 0.1 V)
Min. negative-sequence current $3I_2$	0.05 to 1 A _(1A) / 0.25 to 5 A _(5A) (step 0.01 A)
Inrush current blocking, capable of being activated for each stage	
Component of the 2 nd harmonic	10 to 45 % of the fundamental (step 1 %)
Max. current, which cancels inrush current blocking	0.5 to 25 A _(1A) / 2.5 to 125 A _(5A) (step 0.01 A)

Tele (pilot) protection for directional ground(earth)-fault overcurrent protection (ANSI 85-67N)

Operating modes	Directional comparison: Pickup Directional comparison: Blocking Directional comparison: Unblocking
Additional functions	Echo (see function "weak infeed"); transient blocking for schemes with parallel lines
Transmission and reception signals	Phase-selective signals available for maximum selectivity with single-pole tripping; signals for 2 and 3-end-lines

Weak-infeed protection with undervoltage (ANSI 27WI)

Operating modes with carrier (signal) reception	Echo Echo and trip with undervoltage
Undervoltage phase – ground (earth)	2 to 70 V (step 1 V)
Time delay	0.00 to 30 s (step 0.01 s)
Echo impulse	0.00 to 30 s (step 0.01 s)
Tolerances	
Voltage threshold	≤ 5 % of set value or 0.5 V
Timer	± 1 % of set value or 10 ms

Fault locator

Output of the distance to fault	X, R (secondary) in Ω X, R (primary) in Ω Distance in kilometers or in % of line length
Start of calculation	With trip, with reset of pickup, with binary input
Reactance per unit length	0.005 to 6.5 $\Omega/\text{km}_{(1A)}$ / 0.001 to 1.3 $\Omega/\text{km}_{(5A)}$ (step 0.0001 Ω/km)
Tolerance	For sinusoidal quantities ≤ 2.5 % line length for 30° ≤ φ_{SC} ≤ 90° and $V_{SC}/V_{nom} > 0.1$

Technical data

Voltage protection (ANSI 59, 27)

Operating modes	Local tripping or only indication
Overvoltage protection	
Pickup values $V_{PH-Gnd}>>$, $V_{PH-Gnd}>$ (phase-ground (earth) overvoltage)	1 to 170 V (step 0.1 V) or deactivated
Pickup values $V_{PH-PH}>>$, $V_{PH-PH}>$ (phase-phase overvoltage)	2 to 220 V (step 0.1 V) or deactivated
Pickup values $3V_0>>$, $3V_0>$ ($3V_0$ can be measured via V4 trans- formers or calculated by the relay) (zero-sequence overvoltage)	1 to 220 V (step 0.1 V) or deactivated
Pickup values $V_1>>$, $V_1>$ (positive-sequence overvoltage)	2 to 220 V (step 0.1 V) or deactivated
Measured voltage	Local positive-sequence voltage or calculated remote positive-sequence voltage (compounding)
Pickup values $V_2>>$, $V_2>$ (negative-sequence overvoltage)	2 to 220 V (step 0.1 V) or deactivated
Reset ratio (settable)	0.5 to 0.98 (step 0.01)
Undervoltage protection	
Pickup values $V_{PH-Gnd}<<$, $V_{PH-Gnd}<$ (phase-ground (earth) undervoltage)	1 to 100 V (step 0.1 V) or deactivated
Pickup values $V_{PH-PH}<<$, $V_{PH-PH}<$ (phase-phase undervoltage)	1 to 175 V (step 0.1 V) or deactivated
Pickup values $V_1<<$, $V_1<$ (positive-sequence undervoltage)	1 to 100 V (step 0.1 V) or deactivated
Blocking of undervoltage protection stages	Minimum current; binary input stages
Reset ratio	1.05
Time delays	
Time delay for all over- and undervoltage stages	0 to 100 s (steps 0.01 s) or deactivated
Command / pickup time	Approx. 30 ms
Tolerances	
Voltage limit values	≤ 3 % of setting value or 0.5 V
Time stages	1 % of setting value or 10 ms

Frequency protection (ANSI 81)

Number of frequency elements	4
Setting range	45.5 to 54.5 Hz (in steps of 0.01) at $f_{nom} = 50$ Hz 55.5 to 64.5 Hz (in steps of 0.01) at $f_{nom} = 60$ Hz
Delay times	0 to 600 s or ∞ (in steps of 0.01 s)
Operating voltage range	6 to 230 V (phase-to-ground (earth))
Pickup times	Approx. 80 ms
Dropout times	Approx. 80 ms
Hysteresis	Approx. 20 mHz
Dropout condition	Voltage = 0 V and current = 0 A
Tolerances	
Frequency	12 m Hz for $V = 29$ to 230 V
Delay times	1 % of the setting value or 10 ms

Breaker failure protection (ANSI 50BF)

Number of stages	2
Pickup of current element	0.05 to 20 A _(1A) / 0.25 to 100 A _(5A) (step 0.01 A)
Time delays $T_{1\text{phase}}$, $T_{1\text{3phase}}$, T_2	0 to 30 s (steps 0.01 s) or deactivated
Additional functions	End-fault protection CB pole discrepancy monitoring
Reset time	Approx. 15 ms, typical; 25 ms max.
Tolerances	
Current limit value	≤ 5 % of setting value or 1 % I_{nom}
Time stages	1 % of setting value or 10 ms

Auto-reclosure (ANSI 79)

Number of auto-reclosures	Up to 8
Operating mode	Only 1-pole; only 3-pole, 1 or 3-pole
Operating modes with line voltage check	DLC – dead-line check ADT – adaptive dead time RDT – reduced dead time
Dead times T_{1-ph} , T_{3-ph} , T_{Seq}	0 to 1800 s (step 0.01 s) or deactivated
Action times	0.01 to 300 s (step 0.01 s) or deactivated
Reclaim times	0.5 to 300 s (step 0.01 s)
Start-signal monitoring time	0.01 to 300 s (step 0.01 s)
Additional functions	Synchro-check request 3-phase intertripping InterCLOSE command to the remote end Check of CB ready state Blocking with manual CLOSE
Voltage limit values for DLC, ADT, RDT	
Healthy line voltage	30 to 90 V (step 1 V)
Dead line	2 to 70 V (step 1 V)
Tolerances	
Time stages	1 % of setting value or 10 ms
Voltage limit values	≤ 3 % of setting value or 0.5 V

Synchro-check (ANSI 25)

Initiate options	Auto-reclosure; Manual CLOSE control Control commands
Operating modes with auto-reclosure	Synchro-check Line dead/busbar live Line live/busbar dead Line and busbar dead Bypassing
For manual closure and control commands	As for auto-reclosure
Permissible voltage difference	1 to 60 V (step 0.1 V)
Permissible frequency difference	0.03 to 2 Hz (step 0.01 Hz)
Permissible angle difference	2 to 80 ° (step 1 °)
Max. duration of synchronization	0.01 to 600 s (step 0.01 s) or deactivated
Release delay with synchronous networks	0 to 30 s (step 0.01 s)
Tolerances	
Time stages	1 % of setting value or 10 ms
Voltage limit values	≤ 2 % of setting value or 2 V

Technical data

Restricted earth-fault protection (ANSI 87N)

Multiple availability	2 times (option)
Settings	
Differential current $I_{REF} > I_{Nobj}$	0.05 to 2.00 (steps 0.01)
Limit angle φ_{REF}	110 ° (fixed)
Time delay T_{REF}	0.00 to 60.00 s (steps 0.01 s) or deactivated (no trip)

The set times are pure delay times

Operating times

Pickup time (in ms) at frequency	50 Hz	60 Hz
At 1.5 · setting value $I_{REF} >$, approx.	30	25
At 2.5 · setting value $I_{REF} >$, approx.	28	24
Dropout time (in ms), approx.	26	23
Dropout ratio, approx.	0.7	

Overcurrent-time protection for phase and residual currents

Multiple availability	3 times (option)
Characteristics	
Definite-time stages (DT)	$I_{Ph} >>, 3I_0 >>, I_{Ph} >, 3I_0 >$
Inverse-time stages (IT)	$I_P, 3I_{0P}$
Acc. to IEC	Inverse, very inverse, extremely inverse, long-time inverse
Acc. to ANSI	Inverse, moderately inverse, very inverse, extremely inverse, definite inverse, short inverse, long inverse
	Alternatively, user-specified trip and reset characteristics
Reset characteristics (IT)	Acc. to ANSI with disk emulation

Current stages

High-current stages	$I_{Ph} >>$	0.10 to 35.00 A ¹⁾ (steps 0.01 A) or deactivated (stage ineffective)
	$T_{I_{Ph}} >>$	0.00 to 60.00 s (steps 0.01 s) or deactivated (no trip)
	$3I_0 >>$	0.05 to 35.00 A ¹⁾ (steps 0.01 A) or deactivated (stage ineffective)
	$T_{3I_0} >>$	0.00 to 60.00 s (steps 0.01 s) or deactivated (no trip)
Definite-time stages	$I_{Ph} >$	0.10 to 35.00 A ¹⁾ (steps 0.01 A) or deactivated (stage ineffective)
	$T_{I_{Ph}}$	0.00 to 60.00 s (steps 0.01 s) or deactivated (no trip)
	$3I_0 >$	0.05 to 35.00 A ¹⁾ (steps 0.01 A) or deactivated (stage ineffective)
	$T_{3I_0} >$	0.00 to 60.00 s (steps 0.01 s) or deactivated (no trip)
Inverse-time stages	I_P	0.10 to 4.00 A ¹⁾ (steps 0.01 A)
Acc. to IEC	T_{I_P}	0.05 to 3.20 s (steps 0.01 s) or deactivated (no trip)
	$3I_{0P}$	0.05 to 4.00 A ¹⁾ (steps 0.01 A)
	$T_{3I_{0P}}$	0.05 to 3.20 s (steps 0.01 s) or deactivated (no trip)
Inverse-time stages	I_P	0.10 to 4.00 A ¹⁾ (steps 0.01 A)
Acc. to ANSI	D_{I_P}	0.50 to 15.00 s (steps 0.01 s) or deactivated (no trip)
	$3I_{0P}$	0.05 to 4.00 A ¹⁾ (steps 0.01 A)
	$D_{3I_{0P}}$	0.50 to 15.00 s (steps 0.01 s) or deactivated (no trip)

Thermal overload protection (ANSI 49)

Setting ranges	
Factor k acc. to IEC 60255-8	1 to 4 (steps 0.01)
Time constant τ	1 to 999.9 min (steps 0.1 min)
Temperature alarm stage $\Theta_{alarm}/\Theta_{trip}$	50 to 100 % in relation to the trip temperature
Current alarm stage I_{alarm}	
Secondary 1 A	0.1 to 4 A (step 0.1)
Secondary 5 A	0.5 to 20 A (step 0.1)
Trip time characteristic	$t = \tau \ln \frac{I^2 - I_{pre}^2}{I^2 - (k \cdot I_N)^2}$
Reset ratios	
Θ / Θ_{alarm}	Approx. 0.99
Θ / Θ_{trip}	Approx. 0.99
I / I_{alarm}	Approx. 0.99
Tolerances	Class 10 % acc. to IEC

Trip circuit supervision (ANSI 74TC)

Number of supervisable trip circuits	Up to 3
Number of required binary inputs per trip circuit	1 or 2
Indication relay	1 to 30 s (step 1 s)

Additional functions

Operational measured values

Representation	Primary, secondary and percentage referred to rated value
Currents	$3 \times I_{Phase}; 3I_0; I_{Gnd\ sensitive}; I_1; I_2; I_Y;$ $3I_{0PAR}$ $3 \times I_{Diff}; 3 \times I_{Stab}$
Tolerances	$\leq 0.5\%$ of indicated measured value or $0.5\% I_{nom}$
Voltages	$3 \times V_{Phase-Ground}; 3 \times V_{Phase-Phase}; 3V_0;$ $V_1; V_2; V_{SYNC}; V_{en}; V_{COMP}$
Tolerances	$\leq 0.5\%$ of indicated measured value or $0.5\% V_{nom}$
Power with direction indication	P, Q, S
Tolerances	
P: for $ \cos \varphi = 0.7$ to 1 and $V/V_{nom}, I/I_{nom} = 50$ to 120 %	Typical $\leq 1\%$
Q: for $ \sin \varphi = 0.7$ to 1 and $V/V_{nom}, I/I_{nom} = 50$ to 120 %	Typical $\leq 1\%$
S: for $V/V_{nom}, I/I_{nom} = 50$ to 120 %	Typical $\leq 1\%$
Frequency	f
Tolerance	≤ 20 mHz
Power factor	PF ($\cos \varphi$)
Tolerance for $ \cos \varphi = 0.7$ to 1	Typical $\leq 3\%$
Load impedances with directional indication	$3 \times R_{Phase-Ground}; X_{Phase-Ground}$ $3 \times R_{Phase-Phase}; X_{Phase-Phase}$
Overload measured values	$\Theta/\Theta_{Trip} L1; \Theta/\Theta_{Trip} L2; \Theta/\Theta_{Trip} L3;$ Θ/Θ_{Trip}

Long-term mean values

Interval for derivation of mean value	15 min / 1 min; 15 min / 3 min; 15 min / 15 min
Synchronization instant	Every ¼ hour; every ½ hour; every hour
Values	$3 \times I_{Phase}; I_1; P; P+; P-; Q; Q+; Q-; S$

Technical data**Minimum/maximum memory**

Indication	Measured values with date and time
Resetting	Cyclically Via binary input Via the keyboard Via serial interface
Values	
Min./max. of measured values	3 x I_{Phase} ; I_1 ; 3 x $V_{\text{Phase-Ground}}$; 3 x $V_{\text{Phase-to-phase}}$; 3 V_0 ; V_1 ; P_+ ; P_- ; Q_+ ; Q_- ; S ; f ; power factor (+); power factor (-)
Min./max. of mean values	3 x I_{Phase} ; I_1 ; P ; Q ; S

Energy meters

Four-quadrant meters	W_{P+} ; W_{P-} ; W_{Q+} ; W_{Q-}
Tolerance for $ \cos \varphi > 0.7$ and $V > 50\%$ V_{nom} and $I > 50\%$ I_{nom}	5 %

Oscillographic fault recording

Analog channels	3 x I_{Phase} , 3 I_0 , 3 $I_{0\text{PAR}}$, 3 I_0 Gnd sensitive, 3 x I_{Diff} , 3 x I_{Stab} 3 x V_{Phase} , 3 V_0 , V_{SYNC} , V_{en} , V_x
Max. number of available recordings	8, backed-up by battery if auxiliary voltage supply fails
Sampling intervals	20 samplings per cycle
Total storage time	Approx. 15 s
Binary channels	Pickup and trip information; number and contents can be freely configured by the user
Max. number of displayed binary channels	40

Control

Number of switching units	Depends on the number of binary / indication inputs and indication / command outputs
Control commands	Single command / double command 1, 1 plus 1 common or 2 pole
Feed back	CLOSE, TRIP, intermediate position
Interlocking	Freely configurable
Local control	Control via menu, function keys
Remote control	Control protection, DIGSI, pilot wires

Further additional functions

Measurement supervision	Current sum Current symmetry Voltage sum Voltage symmetry Voltage phase sequence Fuse failure monitor
Annunciations Event logging Fault logging	Buffer size 200 Storage of signals of the last 8 faults, buffer size 800
Switching statistics	Number of breaking operations per c.b. pole Sum of breaking current per phase Breaking current of last trip operation Max. breaking current per phase
Circuit-breaker test	TRIP/CLOSE cycle 3-phase TRIP/CLOSE cycle per phase
Setting range Dead time for CB TRIP/CLOSE cycle	0.00 to 30 s (step 0.01 s) 0.00 to 30 s (step 0.01 s)
Commissioning support	Operational measured values Circuit-breaker test Read binary test Initiate binary inputs Set binary outputs Set serial interface outputs Lockout of a device Test mode of the differential protection topology

CE conformity

This product is in conformity with the Directives of the European Communities on the harmonization of the laws of the Member States relating to electromagnetic compatibility (EMC Council Directive 89/336/EEC) and electrical equipment designed for use within certain voltage limits (Council Directive 73/23/EEC).

This unit conforms to the international standard IEC 60255, and the German standard DIN 57435/Part 303 (corresponding to VDE 0435/Part 303).

Further applicable standards: ANSI/IEEE C37.90.0 and C37.90.1.

The unit has been developed and manufactured for application in an industrial environment according to the EMC standards.

This conformity is the result of a test that was performed by Siemens AG in accordance with Article 10 of the Council Directive complying with the generic standards EN 50081-2 and EN 50082-2 for the EMC Directive and standard EN 60255-6 for the "low-voltage Directive".

Selection and ordering data

Description	Order No.	Short code
7SD5 combined multi-end line differential protection with distance protection	7SD5 □□□ - □□□□ - □□□□ - □□□	

Device type¹⁾

Two-terminal differential relay with 4-line display	2 2
Two-terminal differential relay with graphical display	3 2
Multi-terminal differential relay with 4-line display	2 3
Multi-terminal differential relay with graphical display	3 3

Measurement input

$I_{ph} = 1 \text{ A}^{2)}$, $I_e = 1 \text{ A}^{2)}$	1
$I_{ph} = 1 \text{ A}^{2)}$, $I_e = \text{sensitive (min. = 0.005 A)}$	2
$I_{ph} = 5 \text{ A}^{2)}$, $I_e = 5 \text{ A}^{2)}$	5
$I_{ph} = 5 \text{ A}^{2)}$, $I_e = \text{sensitive (min. = 0.005 A)}$	6

Auxiliary voltage (Power supply, BI trigger level)

24 to 48 V DC, trigger level binary input 19 V ⁴⁾	2
60 to 125 V DC ³⁾ , trigger level binary input 19 V ⁴⁾	4
110 to 250 V DC ³⁾ , 115 V AC, trigger level binary input 88 V ⁴⁾	5
220 to 250 V DC ³⁾ , 115 V AC, trigger level binary input 176 V ⁴⁾	6

Binary / indication inputs	Signal / command outputs incl. one live contact	Fast relays ⁵⁾	High Speed trip outputs ⁶⁾	Housing width referred to 19"	Flush- mounting housing / screw-type terminals	Flush- mounting housing / plug-in terminals	Surface- mounting housing / screw-type terminals	
8	4	12	—	1/2	■			A
8	4	12	—	1/2			■	E
8	4	12	—	1/2		■		J
16	12	12	—	1/1	■			C
16	12	12	—	1/1			■	G
16	12	12	—	1/1		■		L
16	4	15	5	1/1	■			N
16	4	15	5	1/1			■	Q
16	4	15	5	1/1		■		S
24	20	12	—	1/1	■			D
24	20	12	—	1/1			■	H
24	20	12	—	1/1		■		M
24	12	15	5	1/1	■			P
24	12	15	5	1/1			■	R
24	12	15	5	1/1		■		T
24	4	18	10	1/1	■			W

Region-specific default/language settings and function versions

Region GE, German language (can be changed)	A
Region world, English language (can be changed)	B
Region US, US-English language (can be changed)	C
Region world, French language (can be changed)	D
Region world, Spanish language (can be changed)	E
Region world, Italian language (can be changed)	F

1) Redundant prot. data interface for Hot-Standby-service is possible with a two terminal differential relay (second prot. data interface is needed)

2) Rated current 1/5 A can be selected by the means of jumpers.

3) Transition between three auxiliary voltage ranges can be selected by means of jumpers.

4) The binary input thresholds are selectable in three steps by means of jumpers.

5) Fast relays are identified in the terminal diagram. The time advantage compared to signal/command outputs is approx. 3 ms, mainly for protection commands

6) High-speed trip outputs are identified in the terminal diagram. The time advantage compared to fast relays is approx. 5 ms

Selection and ordering data

Description	Order No.	Short code
<i>7SD5 combined multi-end line differential protection with distance protection (continued)</i>	<i>7SD52 □□ - □□□□ - □□□□ - □□□</i>	
<i>System interfaces</i>		
No system interface	0	↑↑↑↑↑↑↑↑↑↑
IEC protocol, electrical RS232	1	↑↑↑↑↑↑↑↑↑↑
IEC protocol, electrical RS485	2	↑↑↑↑↑↑↑↑↑↑
IEC protocol, optical 820 nm, ST-plug	3	↑↑↑↑↑↑↑↑↑↑
PROFIBUS FMS Slave, electrical RS485	4	↑↑↑↑↑↑↑↑↑↑
PROFIBUS FMS Slave, optical 820 nm, twin-ring, ST-plug	6	↑↑↑↑↑↑↑↑↑↑
<i>Further protocols see supplement L</i>	9	L 0 □
PROFIBUS DP slave, RS485		A
PROFIBUS DP slave, optical 820 nm, double ring, ST connector ¹⁾		B
DNP 3.0, RS485		G
DNP 3.0, optical 820 nm, ST connector ¹⁾		H
IEC 61850, 100 Mbit Ethernet, electrical, double, RS45 connector (EN100)		R
IEC 61850, 100 Mbit Ethernet, with integrated switch optical, double, LC-connector (EN100) ²⁾		S
<i>DIGSI/Modem interface (on rear of device) and protection interface 1</i>		
See additional indication M	9	M □ □
<i>DIGSI/Modem interface (on rear of device)</i>		
Without DIGSI-interface on rear	0	↑↑
DIGSI 4, electric RS232	1	↑↑
DIGSI 4, electric RS485	2	↑↑
DIGSI 4, optical 820 nm, ST plug	3	↑↑
<i>Protection data interface 1</i>		
FO5: Optical 820 nm, 2 ST-plugs, line length up to 1.5 km via multimode FO cable for communication converter or direct FO connection ³⁾		A
FO6: Optical 820 nm, 2 ST-plugs, line length up to 3.5 km via multimode FO cable for direct FO connection		B
FO17: Optical 1300 nm, LC-Duplex-plugs, line length up to 24 km via monomode FO cable for direct FO connection ⁴⁾		G
FO18: Optical 1300 nm, LC-Duplex-plugs, line length up to 60 km via monomode FO cable for direct FO connection ⁴⁾⁵⁾		H
FO19: Optical 1550 nm, LC-Duplex-plugs, line length up to 100 km via monomode FO cable for direct FO connection ⁴⁾⁶⁾		J
FO30: Optical 820 nm, 2 ST-plugs, line length up to 1.5 km via multimode FO cable for communication networks with IEEE C37.94 interface or direct FO connection ⁷⁾		S

1) Not possible for surface mounting housing (Order No. pos. 9 = E/G/H/Q/R). For the surface mounted version, please order a device with the appropriate electrical RS485 interface and an external FO-converter

2) Not possible for surface mounting housing (Order No. pos. 9 = E/G/H/Q/R) please order the relay with electrical interface and use a separate fiber-optic switch.

3) Communication converter 7XV5662, see Accessories.

4) Device for surface mounting housing (Order No. pos. 9 = E/G/H/Q/R) will be delivered with external repeater 7XV5461-0Bx00.

5) For distances less than 25 km a set of optical attenuators 7XV5107-0AA00 must be installed to avoid saturation of the receiver element

6) For distances less than 50 km a set of optical attenuators 7XV5107-0AA00 must be installed to avoid saturation of the receiver element

7) Only available in flush-mounting housing (Order No. pos. 9 ≠, E/G/H/Q/R).

Selection and ordering data

Description	Order No.	Short code
7SD5 combined multi-end line differential protection with distance protection (continued)	7SD52 □□ - □□□□ - □□□□ - □□□	

Functions 1 / Protection data interface 2

Trip mode	Auto-reclosure (ANSI 79)	Synchrocheck (ANSI 25)							
3-pole	without	without	0						
3-pole	with	without	1						
1-/3-pole	without	without	2						
1-/3-pole	with	without	3						
3-pole	without	with	4						
3-pole	with	with	5						
1-/3-pole	without	with	6						
1-/3-pole	with	with	7						
With protection data interface 2 see additional specification N									
Relays (Ord.-No. 6 = 2) are available with a second protection data interface (Hot Standby)				9				N	□□

Functions 1

Trip mode	Auto-reclosure (ANSI 79)	Synchrocheck (ANSI 25)							
3-pole	without	without	0						
3-pole	with	without	1						
1-/3-pole	without	without	2						
1-/3-pole	with	without	3						
3-pole	without	with	4						
3-pole	with	with	5						
1-/3-pole	without	with	6						
1-/3-pole	with	with	7						

Protection interface 2

FO5: Optical 820 nm, 2 ST-plugs, line length up to 1.5 km via multimode FO cable for communication converter or direct FO connection ¹⁾	A
FO6: Optical 820 nm, 2 ST-plugs, line length up to 3.5 km via multimode FO cable for direct FO connection	B
FO17: Optical 1300 nm, LC-Duplex-plugs, line length up to 24 km via monomode FO cable for direct FO connection ²⁾	G
FO18: Optical 1300 nm, LC-Duplex-plugs, line length up to 60 km via monomode FO cable for direct FO connection ²⁾³⁾	H
FO19: Optical 1550 nm, LC-Duplex-plugs, line length up to 100 km via monomode FO cable for direct FO connection ²⁾⁴⁾	J
FO 30: Optical 820 nm, 2 ST-plugs, line length up to 1.5 km via multimode FO cable for communication networks with IEEE C37.94 interface or direct FO connection ⁵⁾	S

1) Communication converter 7XV5662, see Accessories.

2) Device for surface mounting housing (Order No. pos. 9 = E/G/H/Q/R) will be delivered with external repeater 7XV5461-0Bx00.

3) For distances less than 25 km a set of optical attenuators 7XV5107-0AA00 must be installed to avoid saturation of the receiver element

4) For distances less than 50 km a set of optical attenuators 7XV5107-0AA00 must be installed to avoid saturation of the receiver element

5) Only available in flush-mounting housing (Order No. pos. 9 ≠, E/G/H/Q/R).

Selection and ordering data

Description

Order No.

Short code

7SD5 combined multi-end line differential protection
with distance protection (continued)

7SD5 □□□ - □□□□□ - □□□□ - □□□

Functions

Time overcurrent protection/
Breaker failure protection (ANSI 50, 50N, 51, 51N, 50BF)

Earth fault protection (ANSI 67N)

Distance protection (Pickup $Z<$, polygon, MHO, parallel line comp.)

Power Swing detection (ANSI 21, 21N, 68, 68T)

Distance protection ($I_{pickup} I>$, $-VI/\varphi$, $-Z<$),
polygon, parallel line comp. ²⁾, power swing det. (ANSI 21, 21N, 68, 68T)

Earth fault detection for
isolated/compensated networks ¹⁾

with	without	without	without	without	C
with	without	without	with	without	D
with	without	with	without	without	E
with	with	without	without	without	F
with	with	without	with	without	G
with	with	with	without	without	H
with	without	without	without	with	J
with	without	without	with	with	K
with	with	without	without	with	L
with	with	without	with	with	M

Additional functions 1

4 Remote commands/24 Remote indications

Transformer expansions

Fault locator

Voltage protection, frequency protection (ANSI 27, 50)

Restricted earth fault low impedance (ANSI 87N) ²⁾

with	without	1-side measuring	without	without	J
with	without	1-side measuring	with	without	K
with	without	2-side measuring	without	without	L
with	without	2-side measuring	with	without	M
with	with	1-side measuring	without	without	N
with	with	1-side measuring	with	without	P
with	with	2-side measuring	without	without	Q
with	with	2-side measuring	with	without	R
with	with	1-side measuring	without	with	S
with	with	1-side measuring	with	with	T
with	with	2-side measuring	without	with	U
with	with	2-side measuring	with	with	V

Additional functions 2

Measured values, extended, Min/Max values

External GPS synchronization

Capacitive current load compensation

without	without	without	0
without	with	without	1
with	without	without	2
with	with	without	3
without	without	with	4
without	with	with	5
with	without	with	6
with	with	with	7

1) Only available with Order No. Pos. 7 = 2 or 6

2) Only available with Order No. Pos. 7 = 1 or 5

Accessories

Description	Order No.
<i>Opto-electric communication converter CC-XG (connection to communication network)</i> Converter to interface to X21 or RS422 or G703-64 kbit/s synchronous communication interfaces Connection via FO cable for 62.5 / 125 µm or 50 / 120 µm and 820 nm wavelength (multi-mode FO cable) with ST connector, max. distance 1.5 km Electrical connection via X21/RS422 or G703-64 kbit/s interface	7XV5662-0AA00
<i>Opto-electric communication converter CC-2M to G703-E1/-T1 communication networks with 2,048/1,554 kbit/s</i> Converter to interface between optical 820 nm interface and G703-E1/-T1 interface of a communication network Connection via FO cable for 62.5/125 µm or 50/120 µm and 820 nm wavelength (multi-mode FO cable) with ST connector, max. distance 1.5 km Electrical connection via G703-E1/-T1 interface	7XV5662-0AD00
<i>Opto-electric communication converter (connection to pilot wire)</i> Converter to interface to a pilot wire or twisted telephone pair (typical 15 km length) Connection via FO cable for 62.5/125 µm or 50/120 µm and 820 nm wavelength (multi-mode FO cable) with ST connector; max. distance 1.5 km, screw-type terminals to pilot wire	7XV5662-0AC00
<i>Additional interface modules</i> Protection data interface mod. opt. 820 nm, multi-mode FO cable, ST connector, 1.5 km Protection data interface mod. opt. 820 nm, multi-mode FO cable, ST connector, 3.5 km	C53207-A351-D651-1 C53207-A351-D652-1
<i>Further modules</i> Protection data interface mod. opt. 1300 nm, mono-mode FO cable, LC-Duplex connector, 24 km Protection data interface mod. opt. 1300 nm, mono-mode FO cable, LC-Duplex connector, 60 km Protection data interface mod. opt. 1550 nm, mono-mode FO cable, LC-Duplex connector, 100 km	C53207-A351-D655-1 C53207-A351-D656-1 C53207-A351-D657-1
<i>Optical repeaters</i> Serial repeater (2-channel), opt. 1300 nm, mono-mode FO cable, LC-Duplex connector, 24 km Serial repeater (2-channel), opt. 1300 nm, mono-mode FO cable, LC-Duplex connector, 60 km Serial repeater (2-channel), opt. 1550 nm, mono-mode FO cable, LC-Duplex connector, 100 km	7XV5461-0BG00 7XV5461-0BH00 7XV5461-0BJ00
<i>Time synchronizing unit with GPS output</i> GPS 1 sec pulse and time telegram IIRIG B/DCF 77	7XV5664-0AA00
<i>Isolation transformer (20 kV) for pilot wire communication</i>	7XR9516
<i>Voltage transformer miniature circuit-breaker</i> Rated current 1.6 A; thermal overload release 1.6 A; overcurrent trip 6 A	3RV1611-1AG14

Accessories

Description	Order No.
DIGSI 4 Software for configuration and operation of Siemens protection units running under MS Windows (Windows 2000 or XP Professional) device templates, Comtrade Viewer, electronic manual included as well as "Getting started" manual on paper, connecting cables (copper)	
Basis Full version with license for 10 computers, on CD-ROM (authorization by serial number)	7XS5400-0AA00
Professional DIGSI 4 Basis and additionally SIGRA (fault record analysis), CFC Editor (logic editor), Display Editor (editor for default and control displays) and DIGSI 4 Remote (remote operation)	7XS5402-0AA00
SIGRA 4 (generally contained in DIGSI Professional, but can be ordered additionally) Software for graphic visualization, analysis and evaluation of fault records. Can also be used for fault records of devices of other manufacturers (Comtrade format). Running under MS Windows (Windows 2000 or XP Professional). Incl. templates, electronic manual with license for 10 PCs. Authorization by serial number. On CD-ROM.	7XS5410-0AA00
Connecting cable Cable between PC/notebook (9-pin connector) and protection unit (9-pin connector) (contained in DIGSI 4, but can be ordered additionally)	7XV5100-4
Manual for 7SD522/523 V4.6 English	C53000-G1176-C169



Fig. 7/78 Mounting rail for 19" rack

Fig. 7/79
2-pin connectorFig. 7/80
3-pin connectorFig. 7/81
Short-circuit link
for current
contactsFig. 7/82
Short-circuit link
for voltage
contacts/
indications
contacts

Description	Order No.	Size of package	Supplier	Fig.
Connector	2-pin	1	Siemens	7/79
	3-pin	1	Siemens	7/80
Crimp connector	CI2 0.5 to 1 mm ²	4000	AMP ¹⁾	
		1	AMP ¹⁾	
	CI2 1 to 2.5 mm ²	4000	AMP ¹⁾	
		1	AMP ¹⁾	
Crimping tool	Type III+ 0.75 to 1.5 mm ²	4000	AMP ¹⁾	
		1	AMP ¹⁾	
	For Type III+ and matching female	1	AMP ¹⁾	
	For CI2 and matching female	1	AMP ¹⁾	
19"-mounting rail	C73165-A63-D200-1	1	Siemens	7/78
Short-circuit links	For current terminals	1	Siemens	7/81
	For other terminals	1	Siemens	7/82
Safety cover for terminals	large	1	Siemens	
	small	1	Siemens	

1) Your local Siemens representative can inform you on local suppliers.

Connection diagram

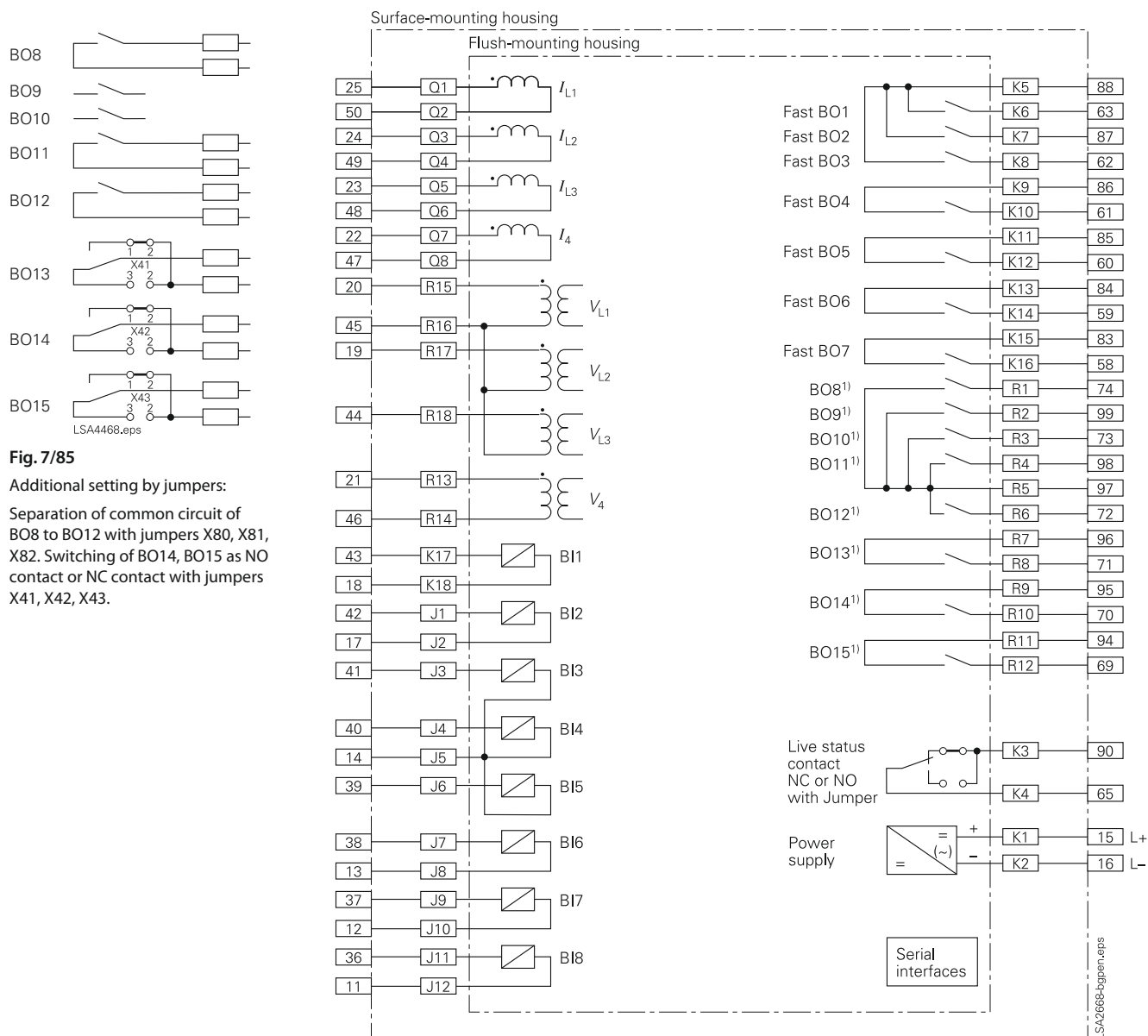


Fig. 7/83 Basic version in housing 1/2 x 19" with 8 binary inputs and 16 binary outputs

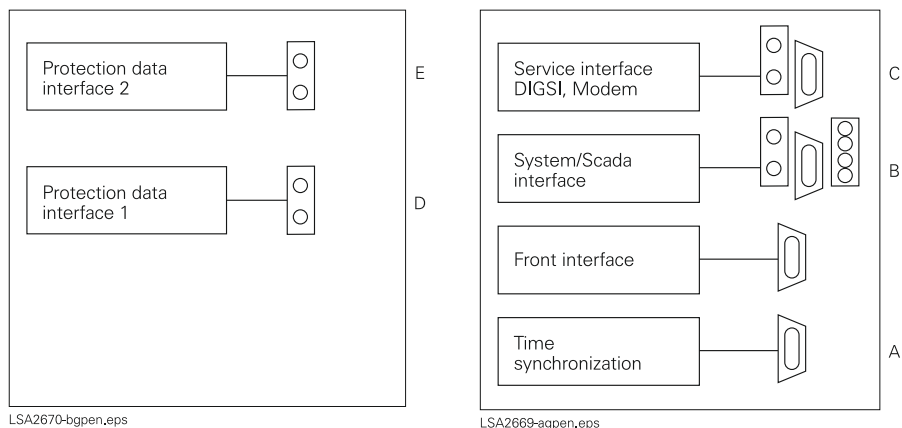


Fig. 7/84 Serial interfaces

1) Configuration of binary outputs until Hardware-version /EE. For advanced flexibility see Fig. 7/85.

Connection diagram

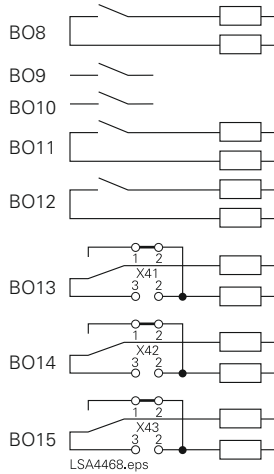


Fig. 7/87

Additional setting by jumpers:

Separation of common circuit of BO8 to BO12 with jumpers X80, X81, X82. Switching of BO14, BO15 as NO contact or NC contact with jumpers X41, X42, X43.

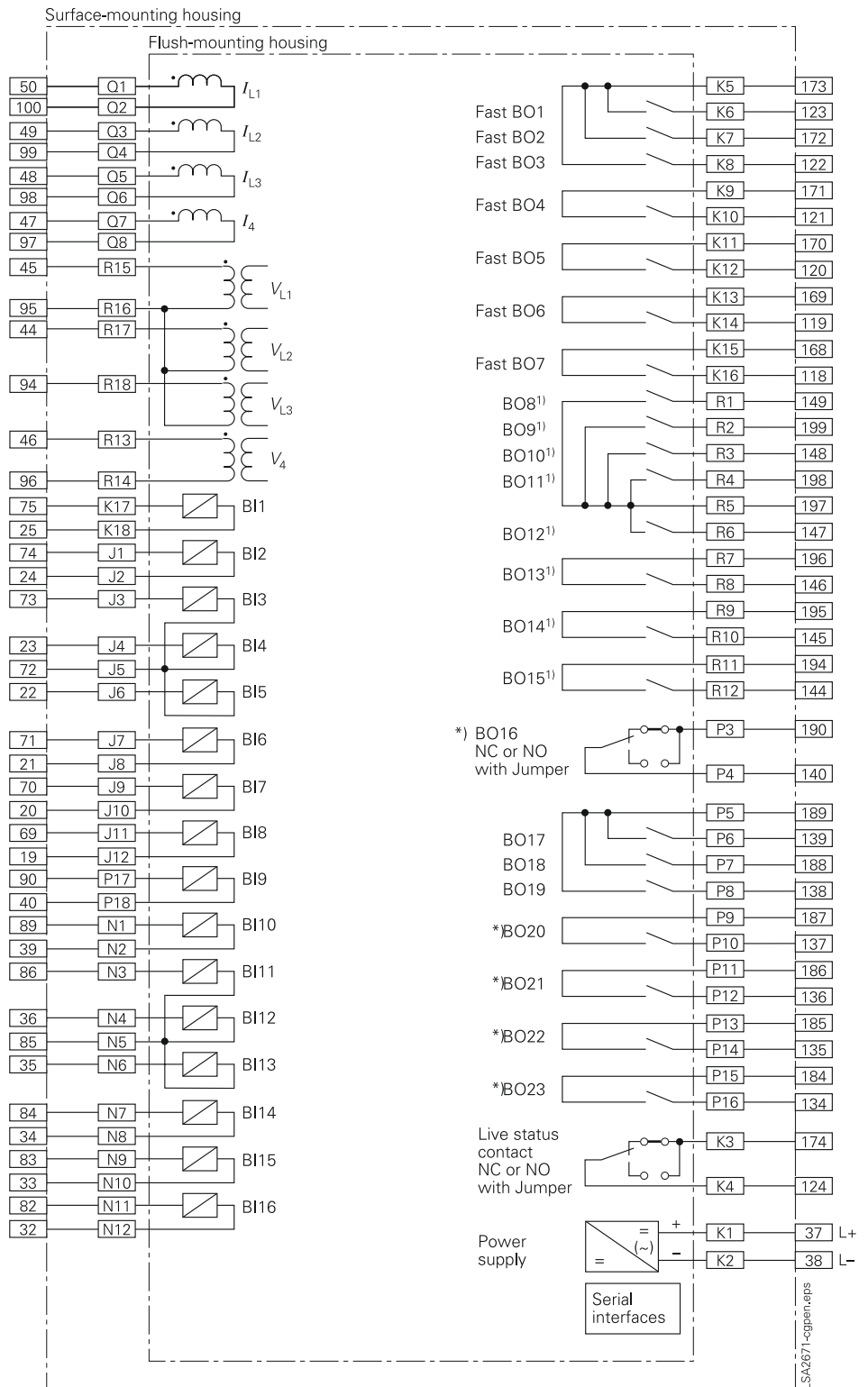


Fig. 7/86 Medium version in housing 1/1 x 19"

*) For unit version 7SD52xx-xN/S/Q high-speed contacts

1) Configuration of binary outputs until Hardware-version /EE. For advanced flexibility see Fig. 7/87.

Connection diagram

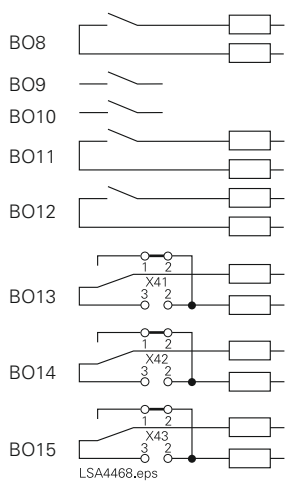


Fig. 7/89

Additional setting by jumpers:

Separation of common circuit of BO8 to BO12 with jumpers X80, X81, X82. Switching of BO14, BO15 as NO contact or NC contact with jumpers X41, X42, X43.

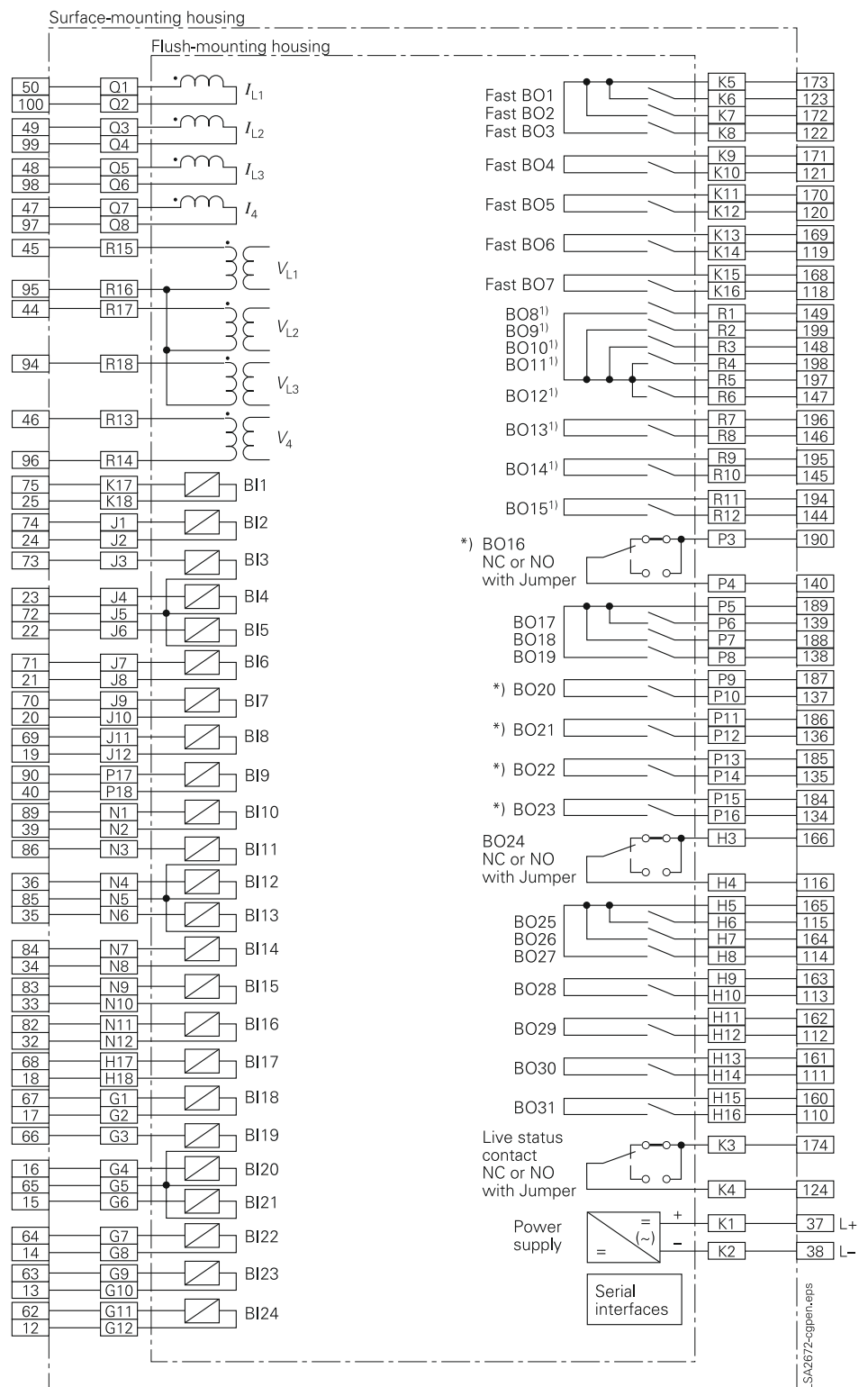


Fig. 7/88 Maximum version in housing 1/1 x 19"

*) For unit version 7SD52xx-xR/P/T high-speed contacts

1) Configuration of binary outputs until Hardware-version /EE. For advanced flexibility see Fig. 7/89.